

Progress in (Hadamard-coded) multiplexing of Transition Edge Sensors

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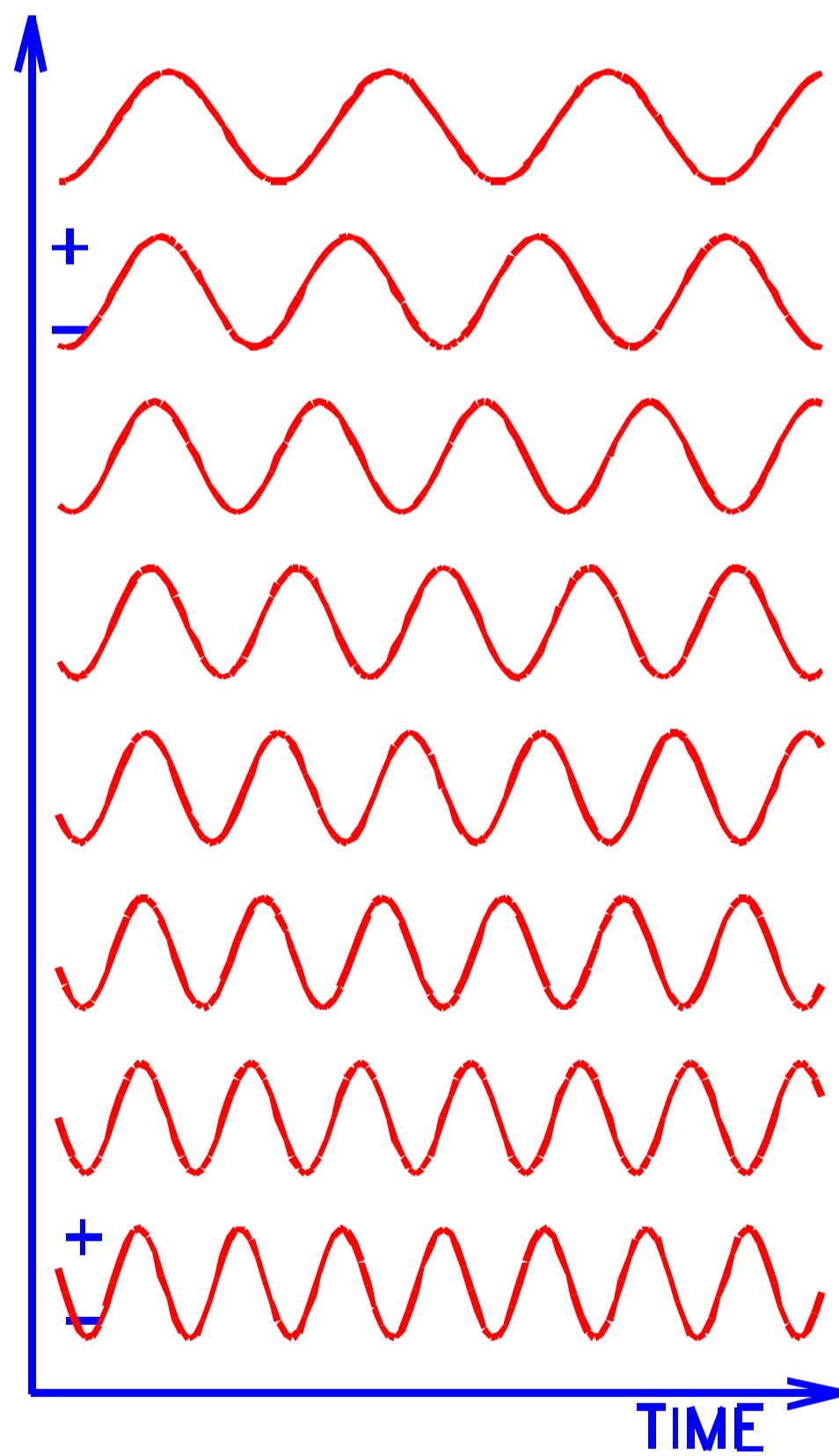
Aivon Oy, Finland

Stuff covered:

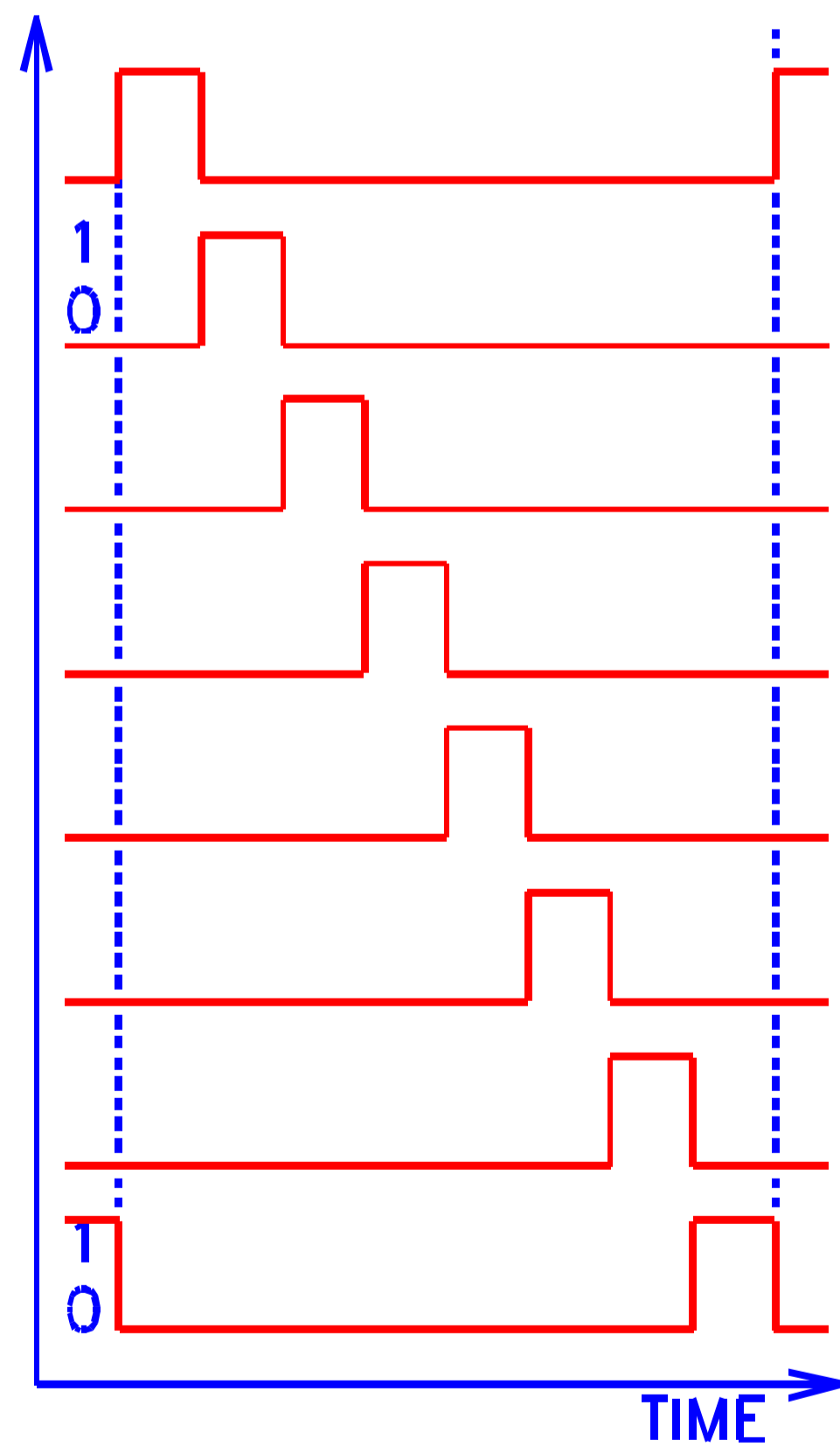
- Hadamard coding with current steering switches
 - Still in progress: difficulties with switch operation
- TD multiplexer using 3-junction interferometers as switches, for pixel characterization
 - Multiplexer works, experiment with real TESes in progress
- Binary addressing utilizing Hadamard codes and periodicity of the SQUID response
 - Demonstrated by slope-switching SQUIDs and test loads

Orthogonal basis sets for multiplexing

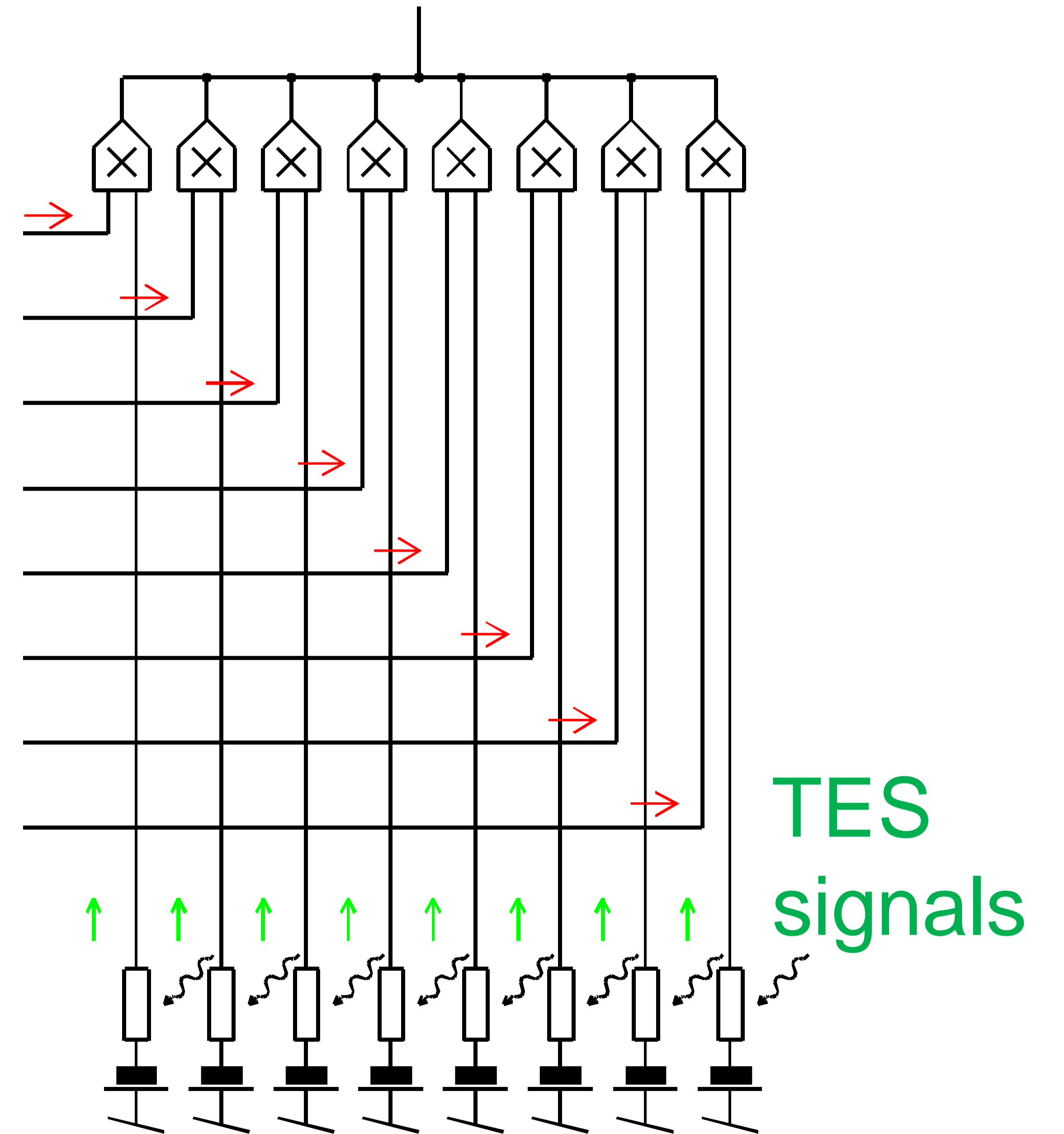
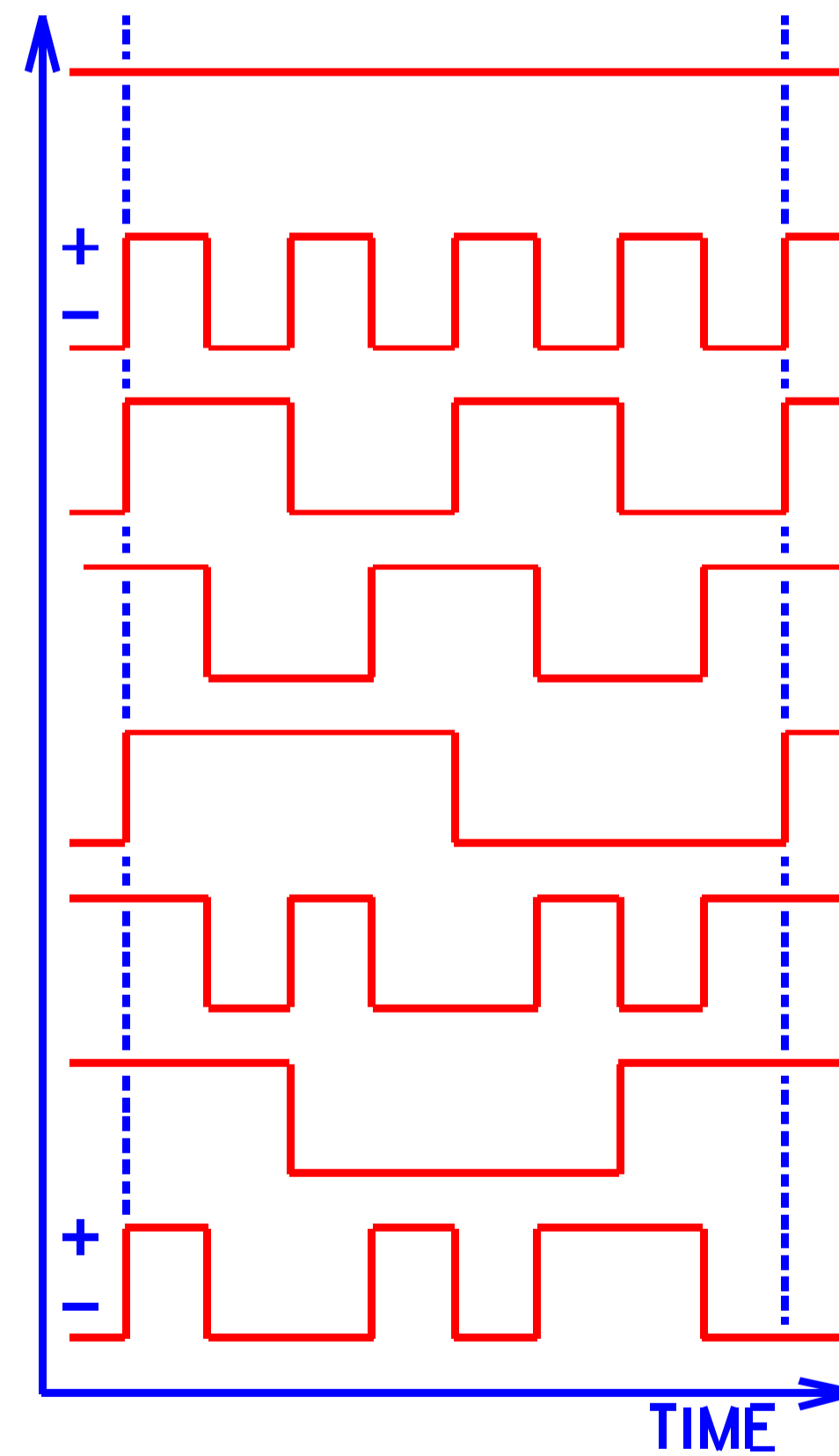
Frequency domain



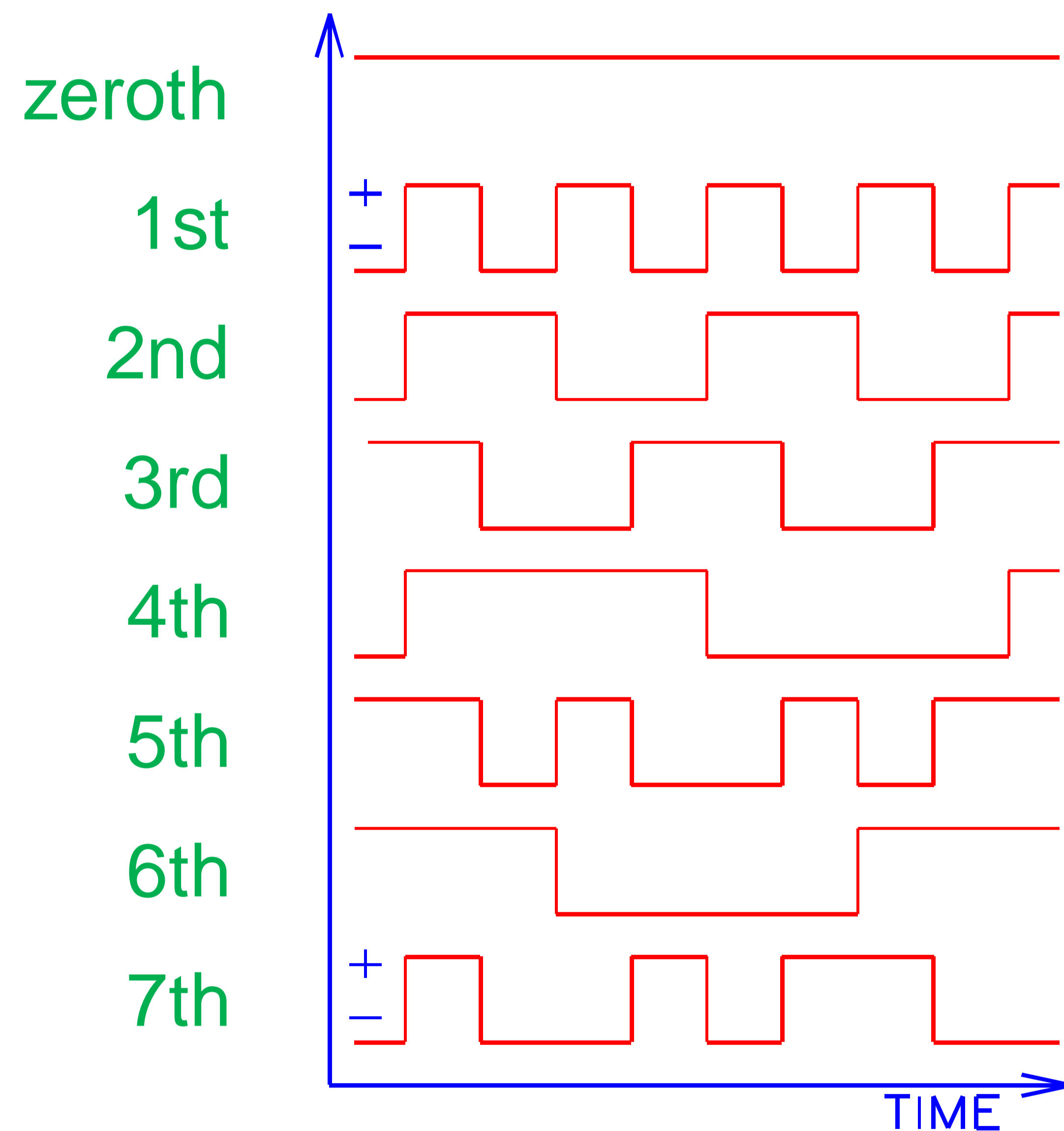
Time domain



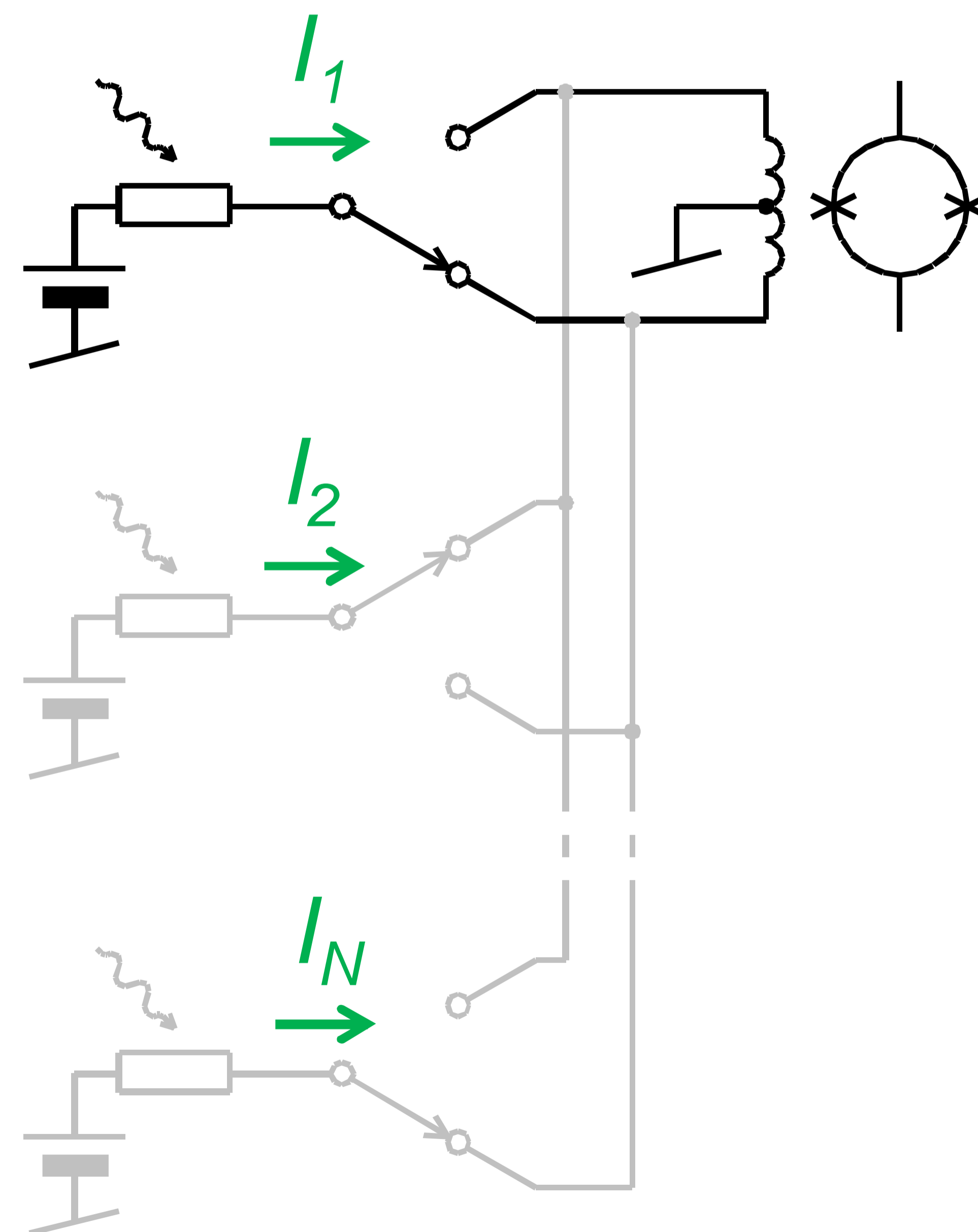
Hadamard - Walsh



Hadamard (Walsh) codes



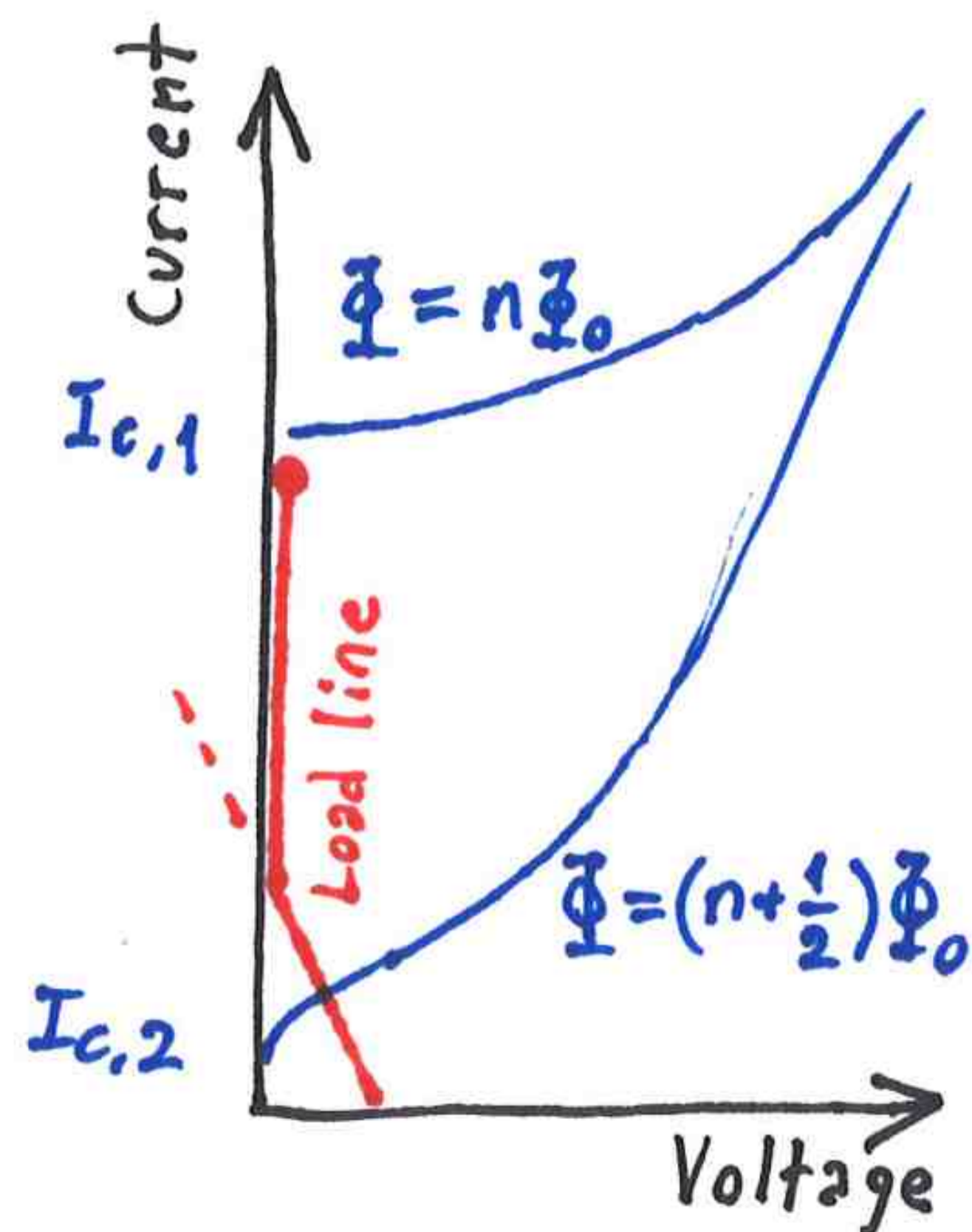
Codes are **bipolar two-level**
⇒ multiplication by a
commutating switch



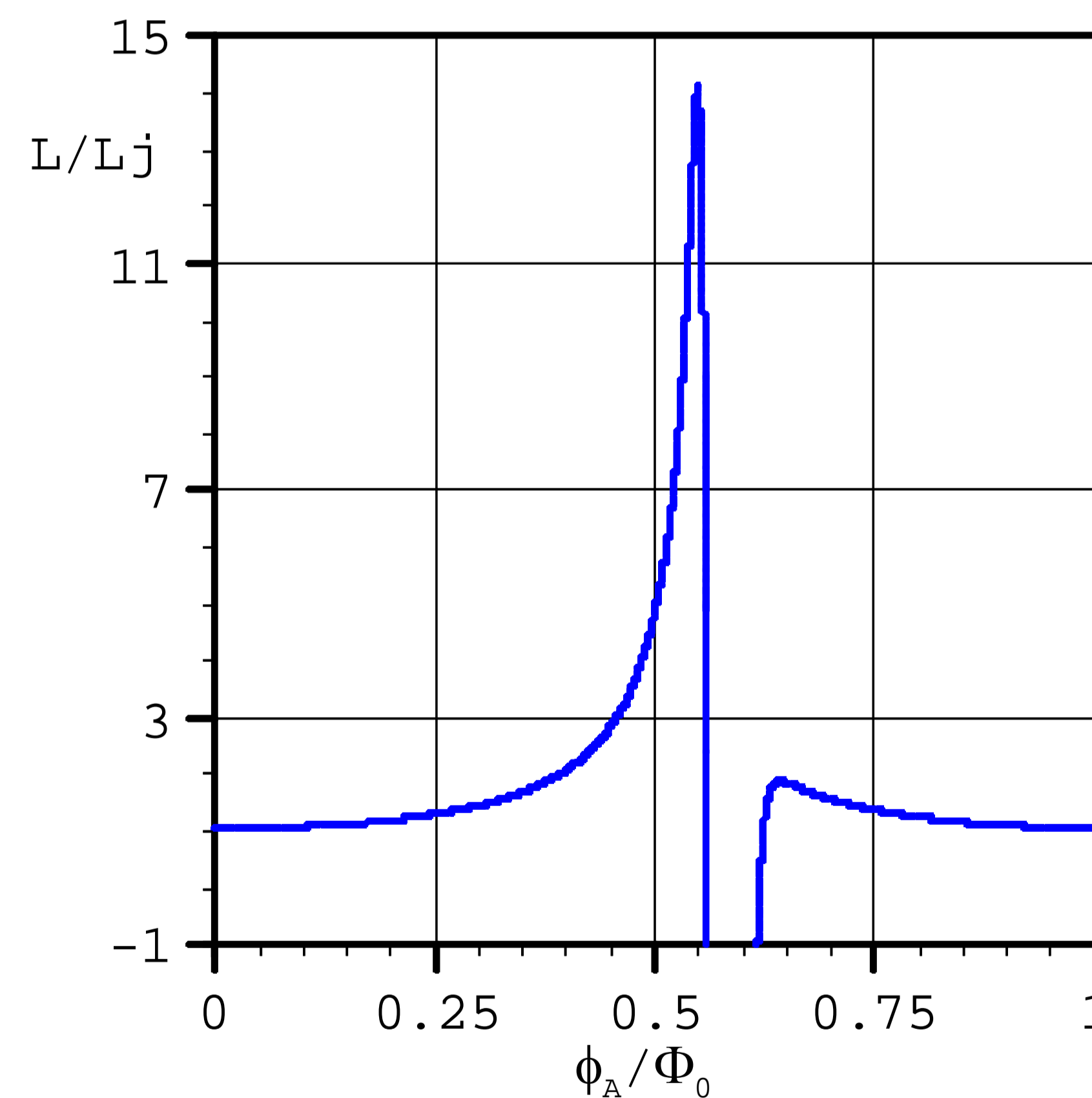
JJ based current steering switches

Low- β_L SQUID,
voltage state

(J.Beyer, SuST 2008)



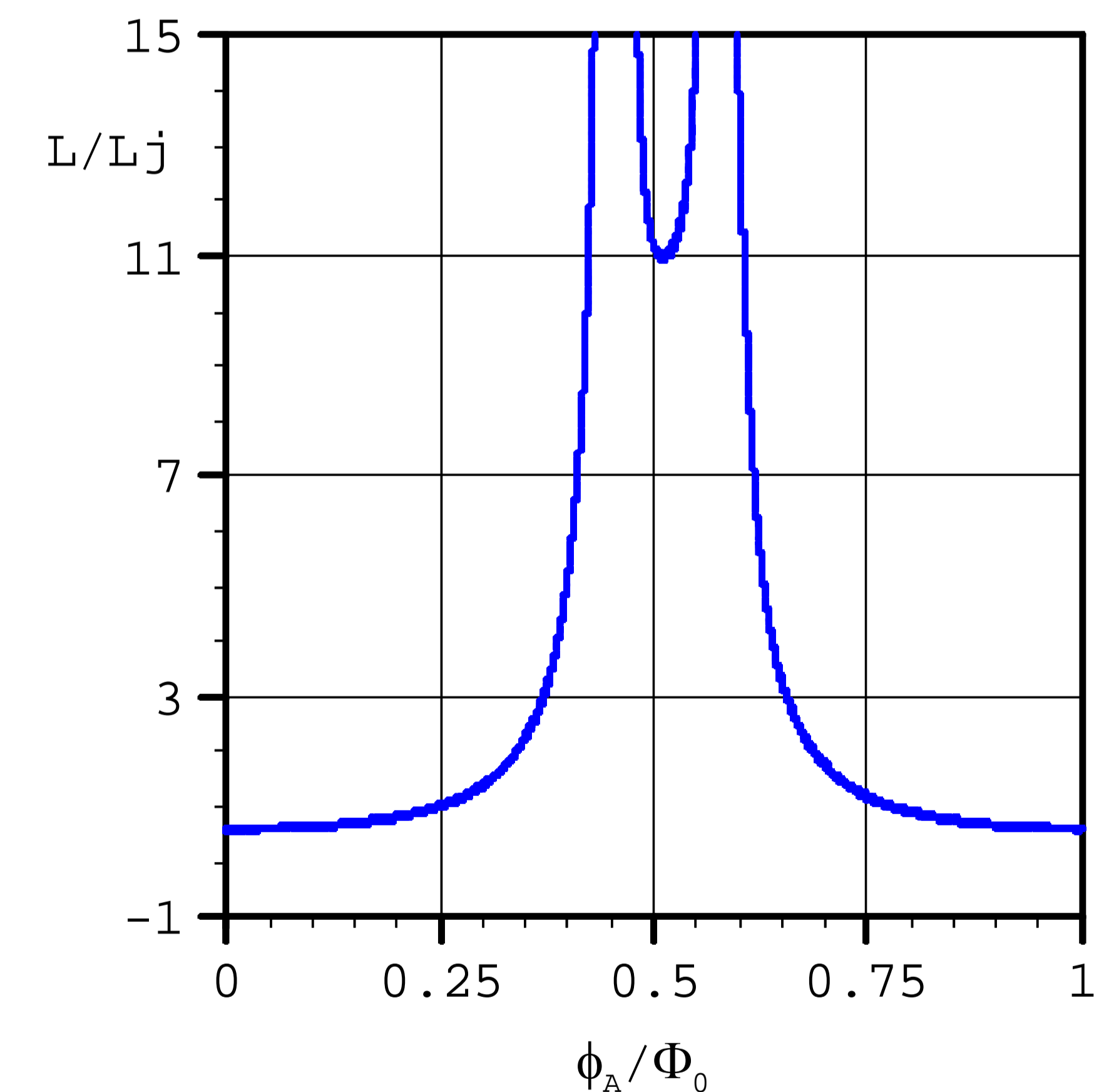
Low- β_L SQUID, as
controlled inductance



$$L_J = \frac{\Phi_0}{2\pi I_C \cos \phi_A}$$

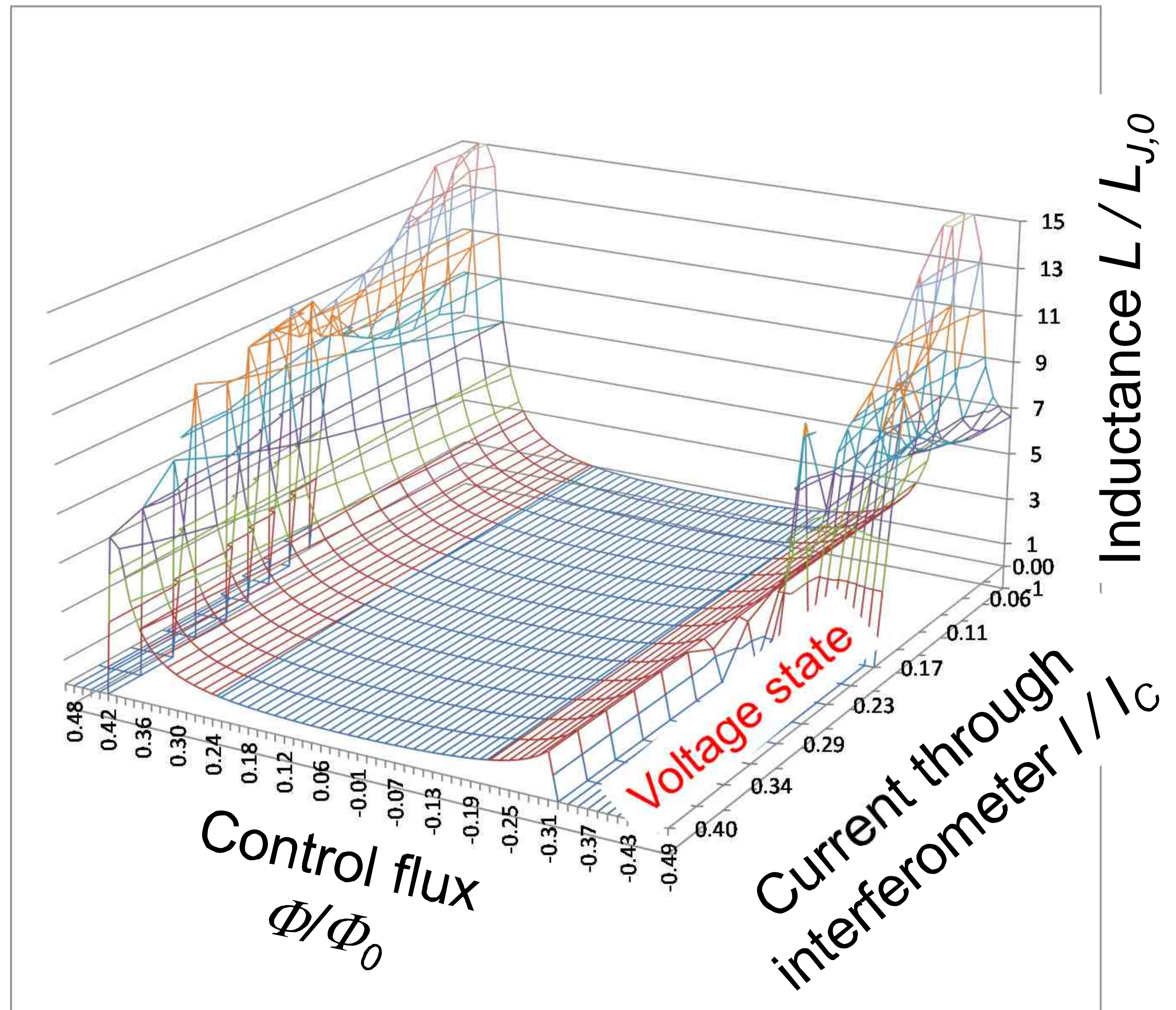
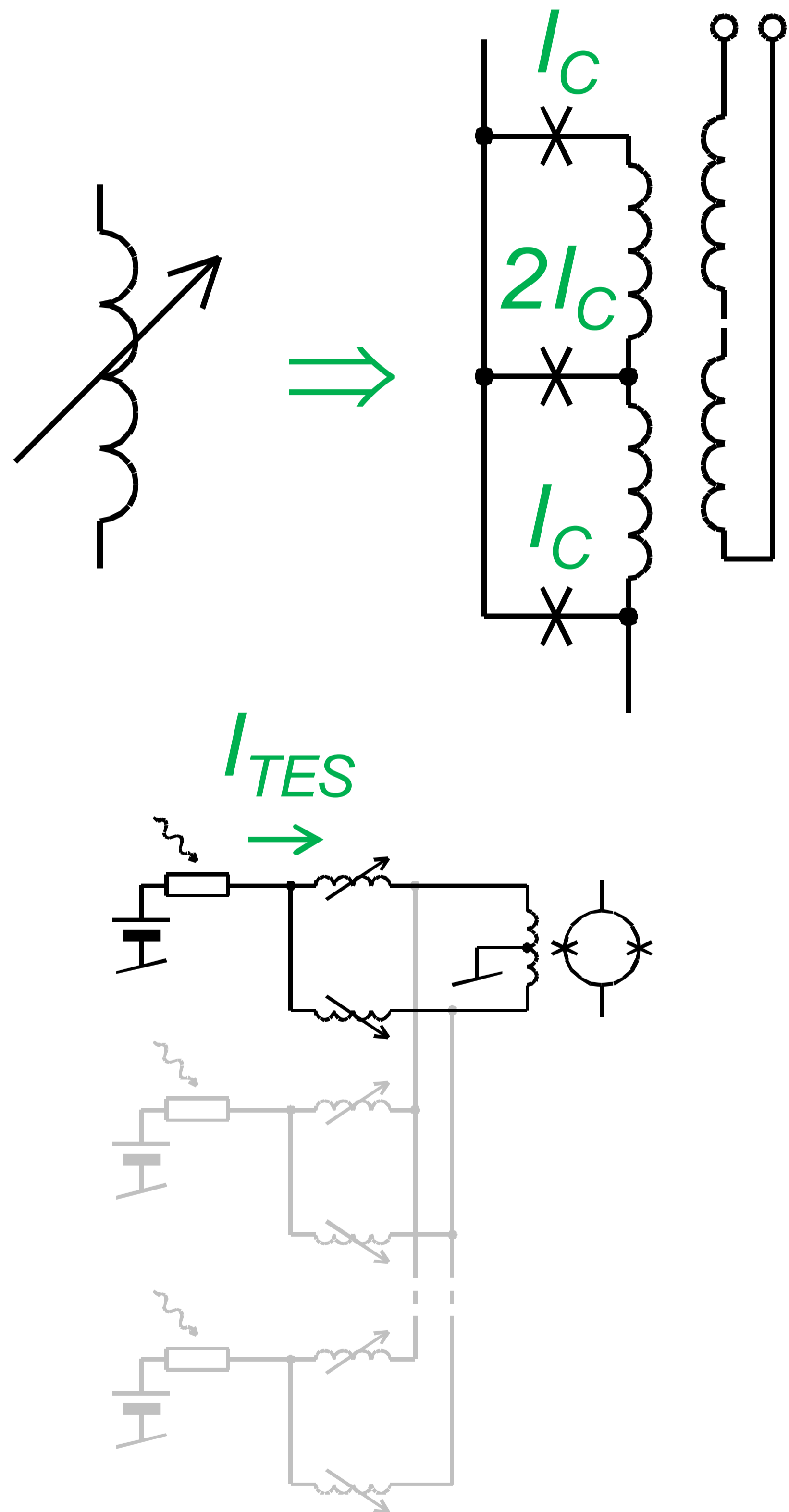
Zappe interferometer,
controlled inductance

(J.Ullom, LT26 presentation, 2011
H. Zappe, IEEE Trans. Magn. 1977))

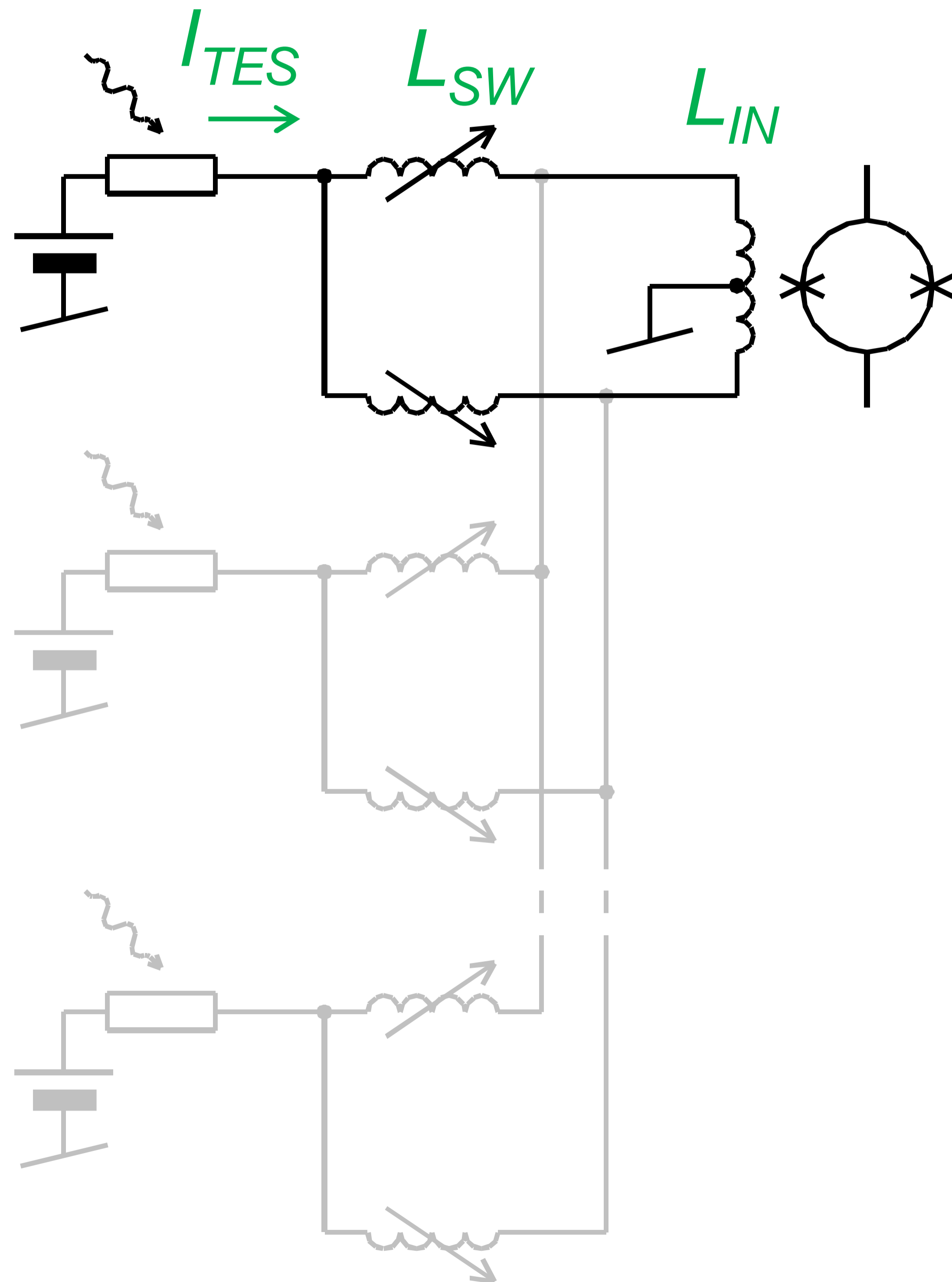


Josephson
inductance

Inductive CS switch: dynamic range



Inductive CS switch: dynamic range



Current noise \leftrightarrow SQUID energy resol.

$$I_{N,SQ} = \sqrt{\frac{\varepsilon}{2L_{IN}}}$$

L_{SW} and max. current are related

$$I_{MAX,SW} \sim \frac{\Phi_0}{2\pi L_{SW}}$$

Must be dominated by controlled- L

$$L_{SW} \gg L_{IN}$$

L_{SW} becomes small, lets use N in series

$$D \equiv \frac{I_{MAX}}{I_N} \sim \sqrt{N}$$

Switch = array
of interferometers

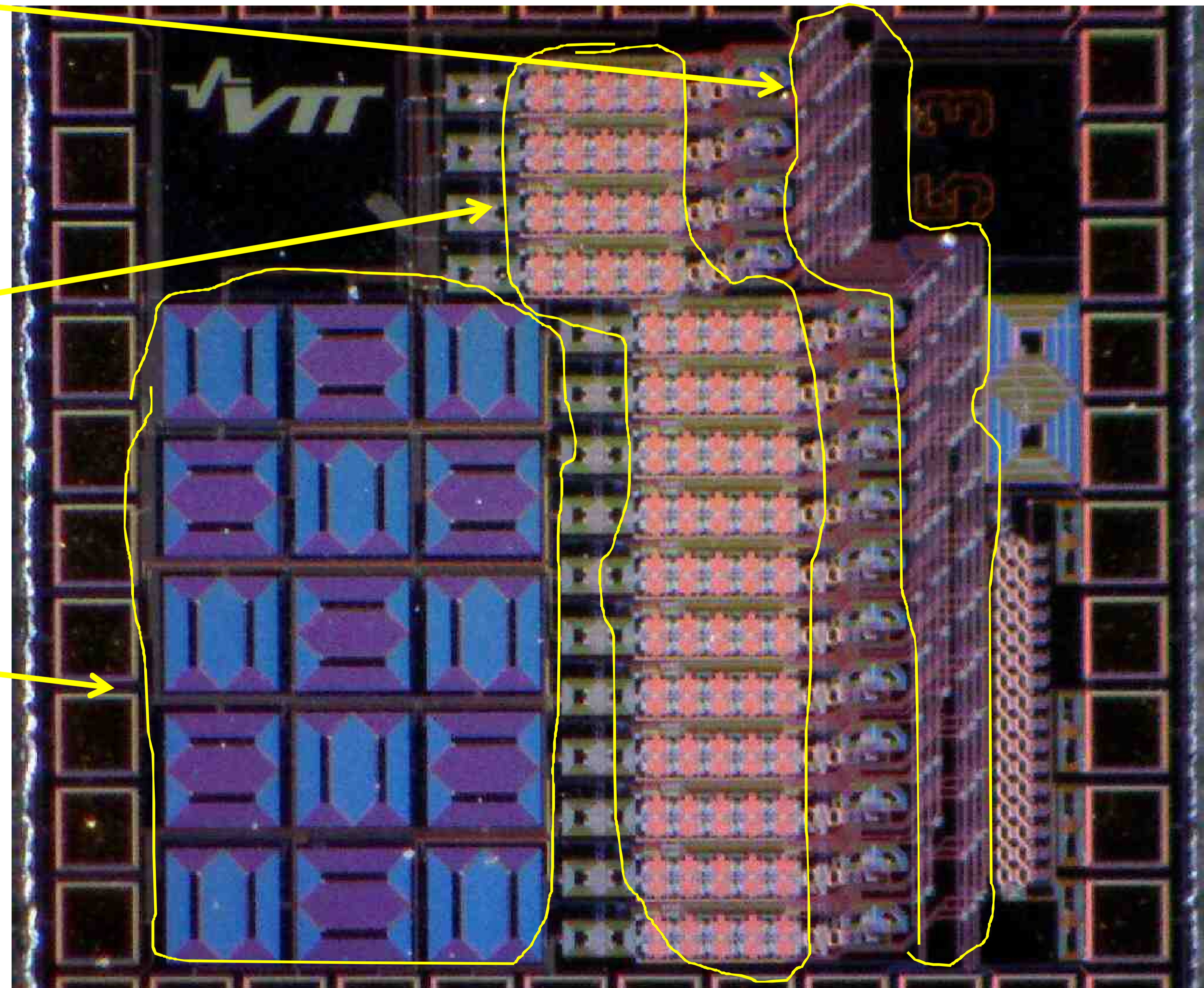
15-channel CDM MUX chip

Binary-to-Hadamard
coding matrix
(explained soon)

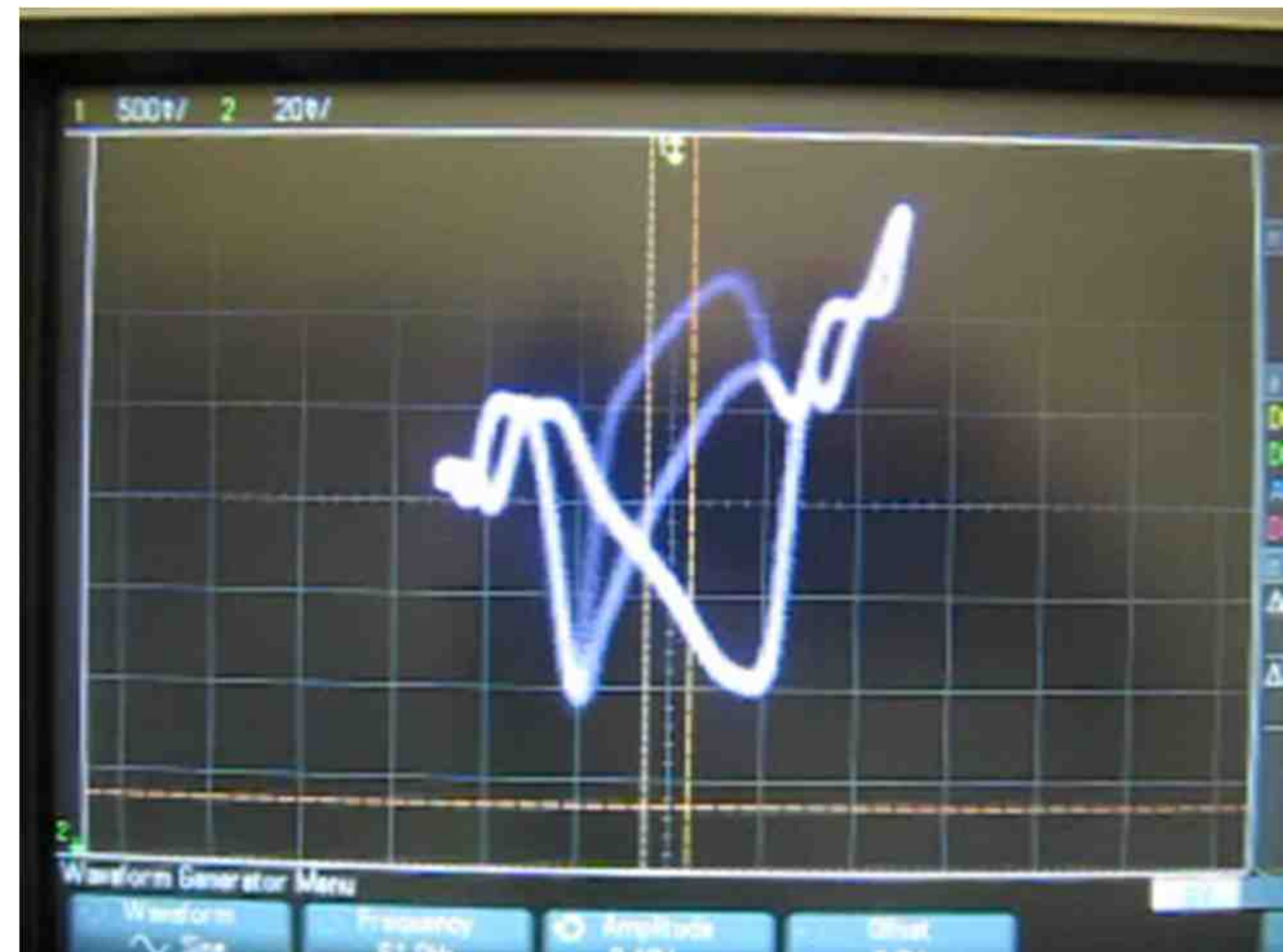
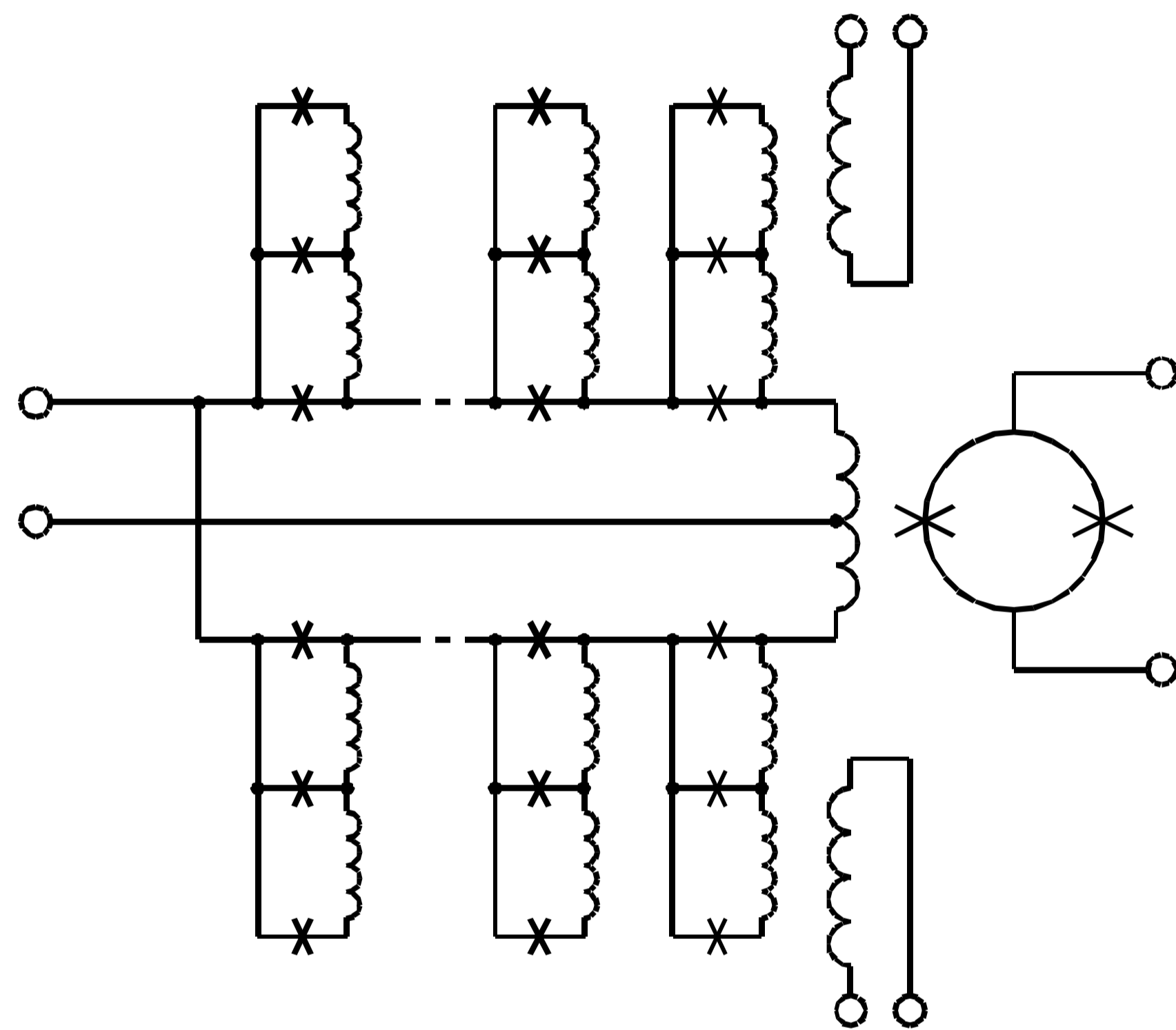
Current steering
switches: **10** Zappe
interferometers
in series

Antialias
filters

Functions in
a strange way!



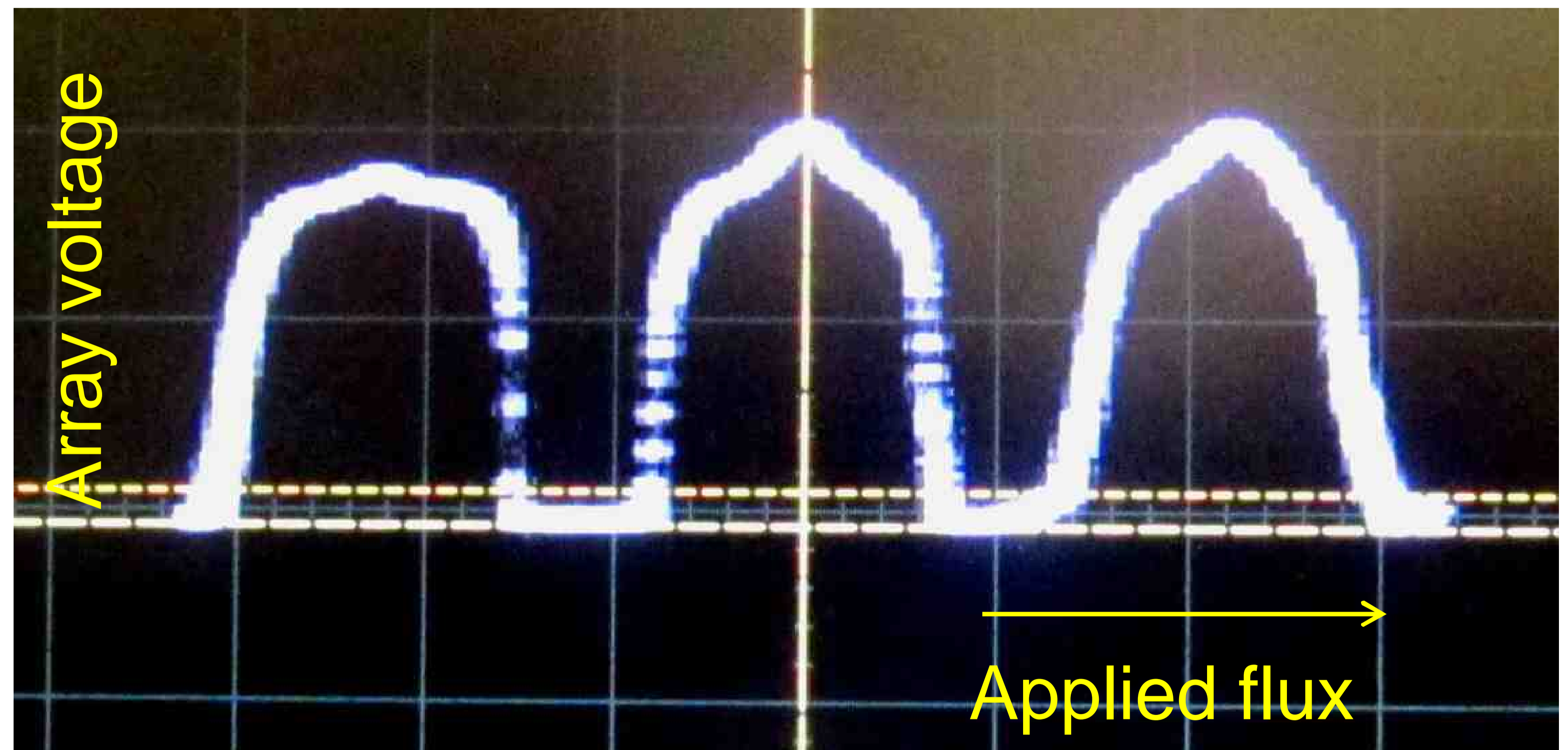
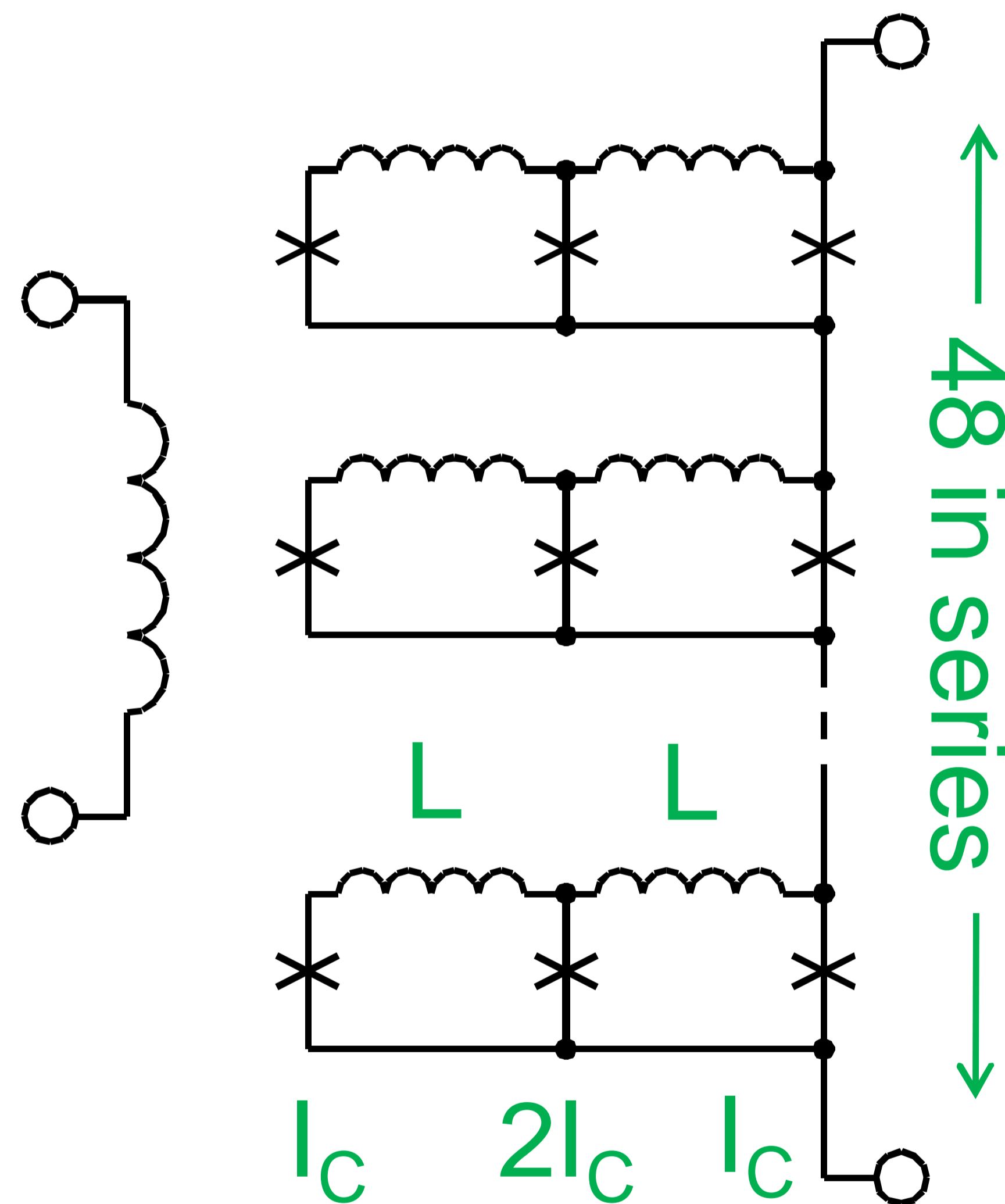
Current steering test switch, inductive mode



Response not exactly what we anticipated!

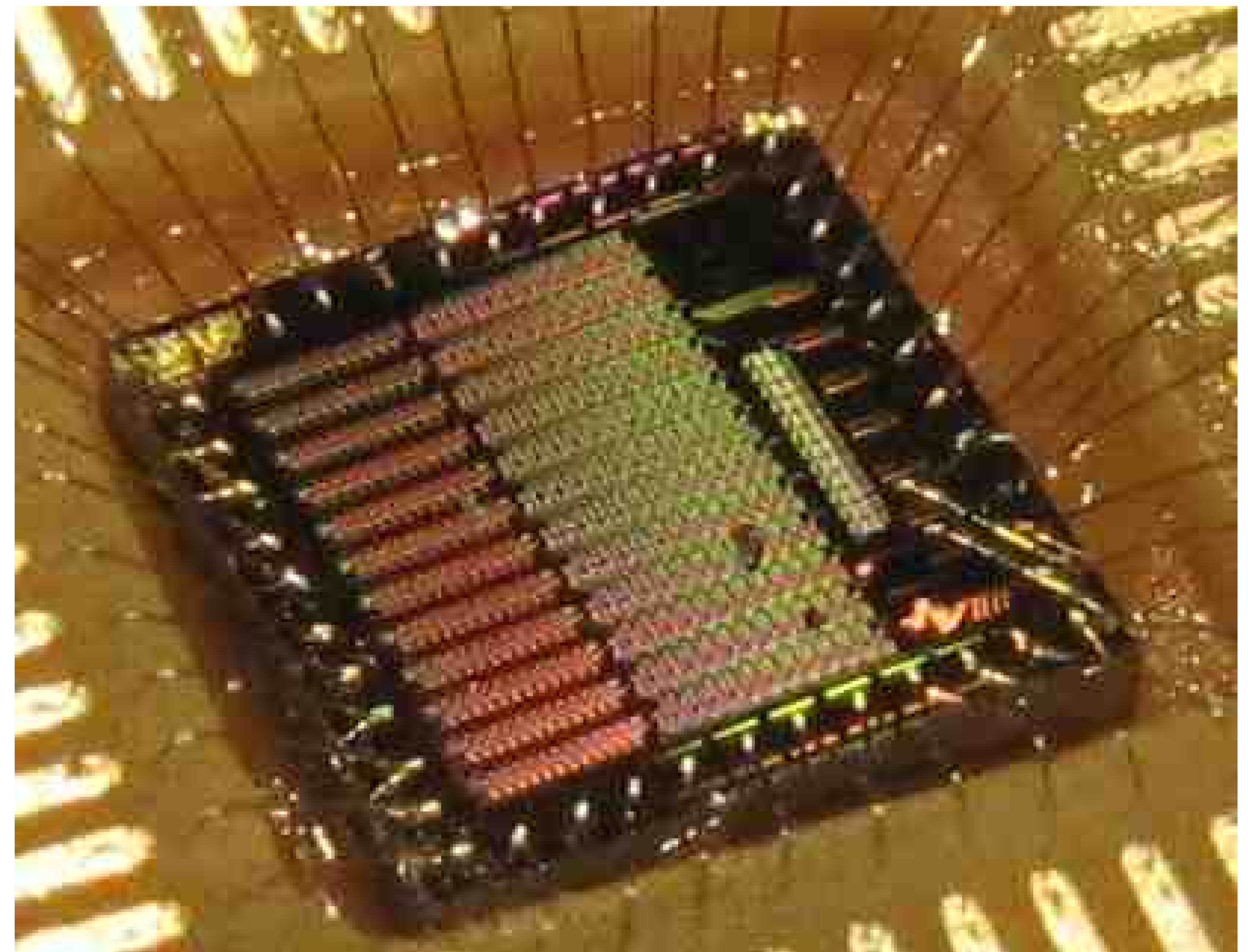
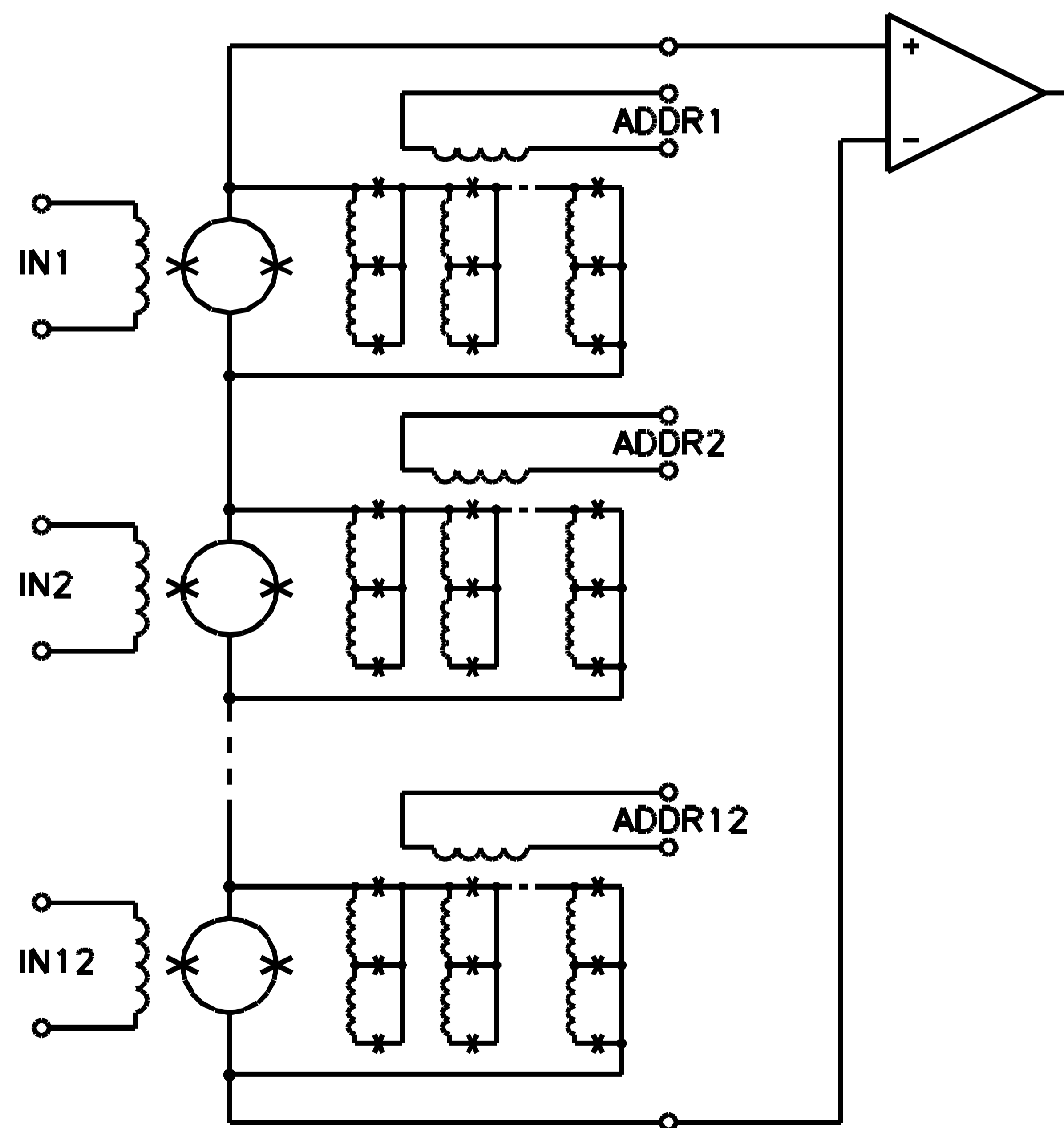
- Flux trapping in inductive mode (not in voltage mode)?
- Back-action from readout SQUID?
- Strong envelope in interference pattern?

Zappe interferometer arrays in voltage state



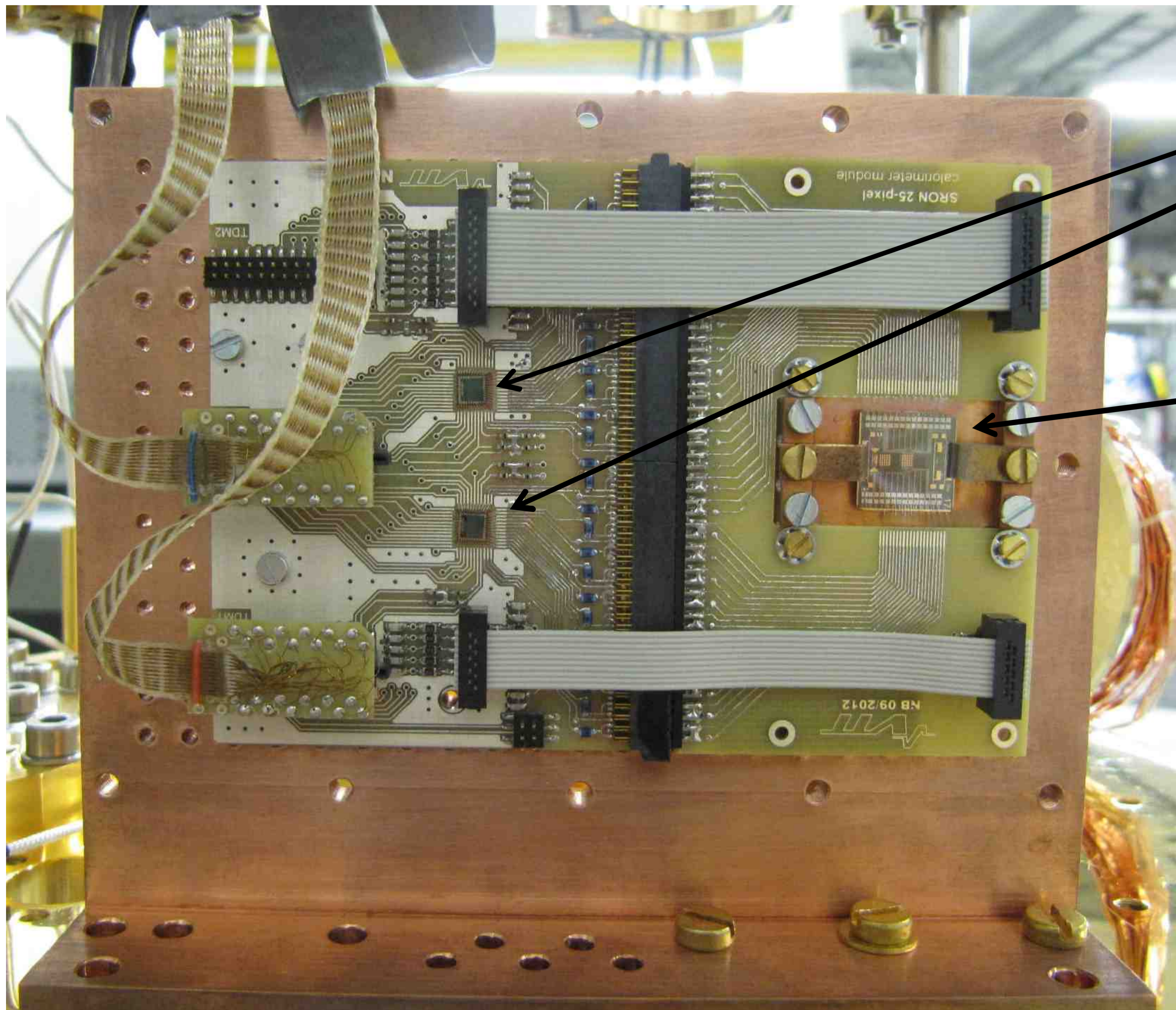
They function nicely as expected!

12-channel Beyer-style time domain MUX using voltage-state Zappe switches



Works nicely at 4.2K with test loads

Experimental 100mK TDM calorimeter setup



1:12 TDM
MUX chips

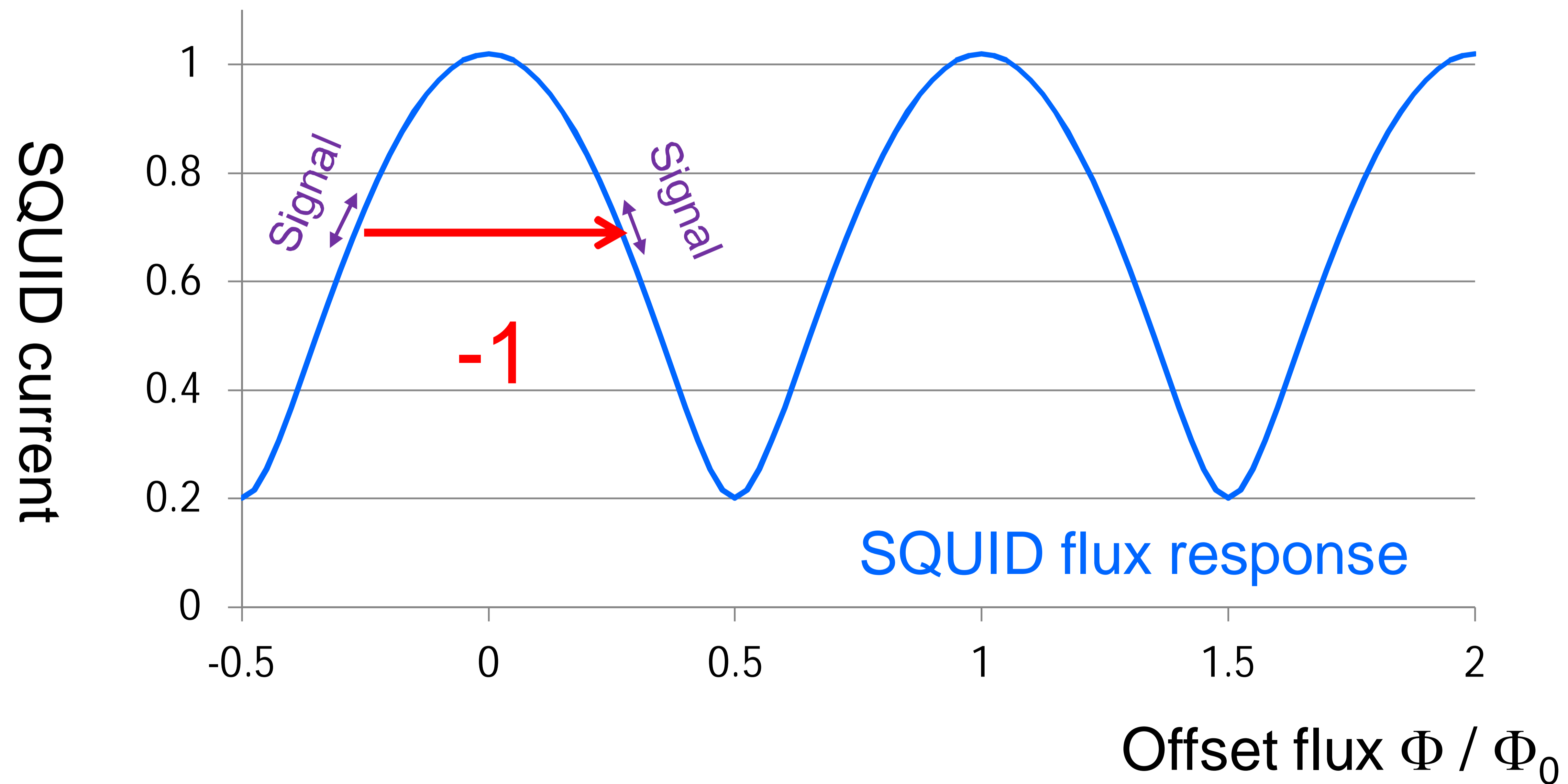
5 x 5 X-ray
calorimeter
array (SRON)

So far suffers from
heat leakage through
the Faraday cage
structure \Rightarrow **no data yet**

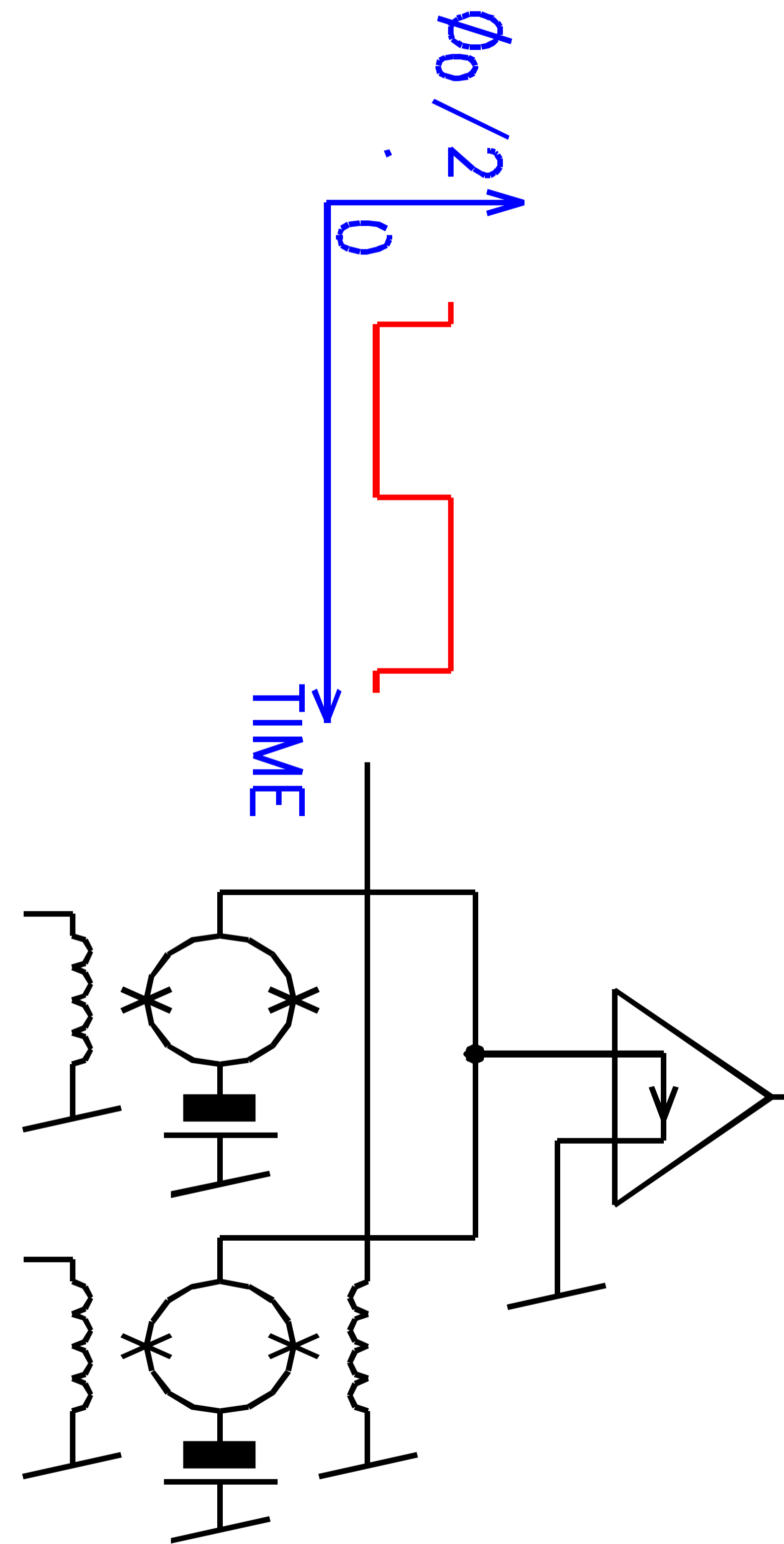
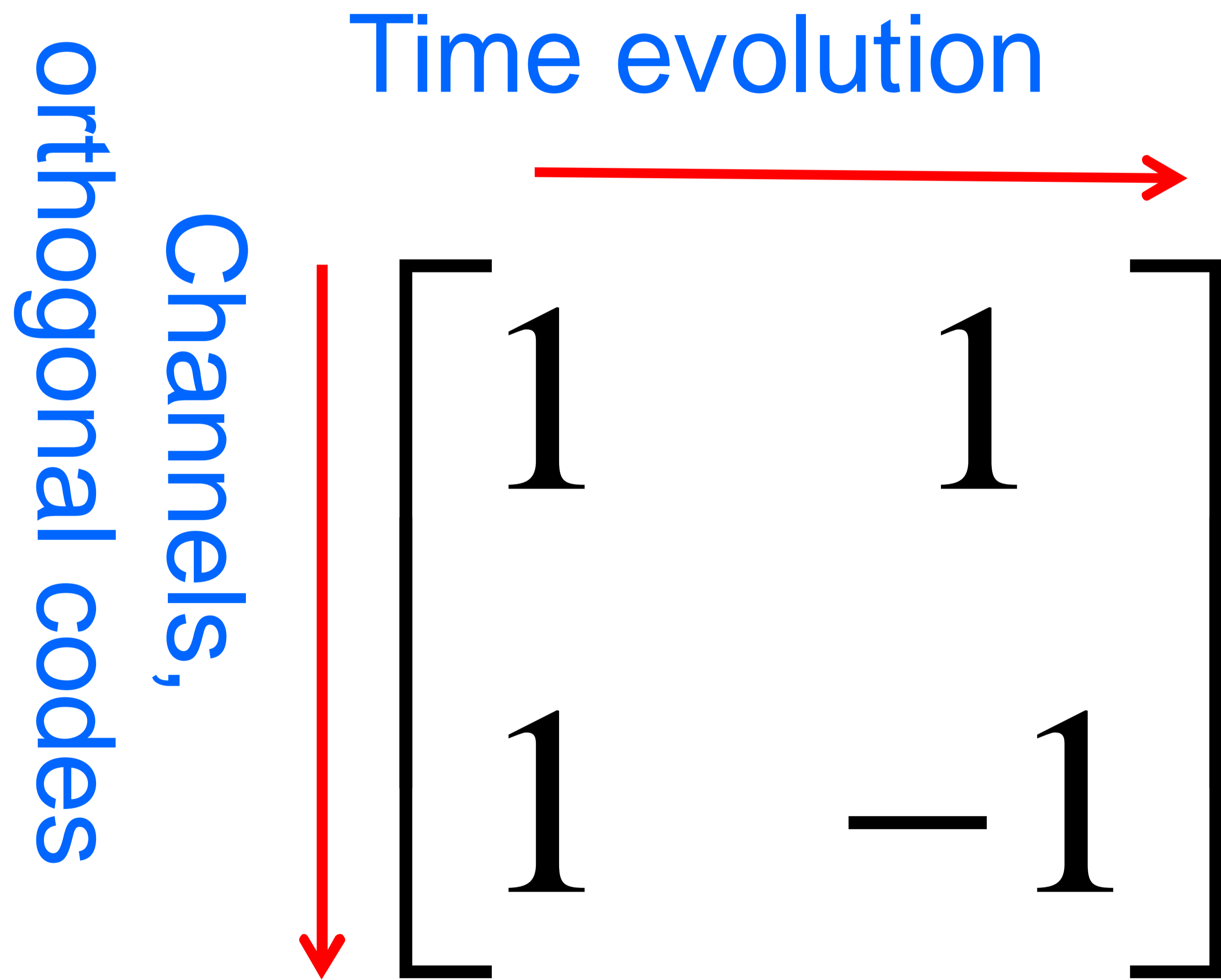
Binary-to-Hadamard coding

(originally K. Irwin, SuST 2010)

SQUID slope change as the commutating switch

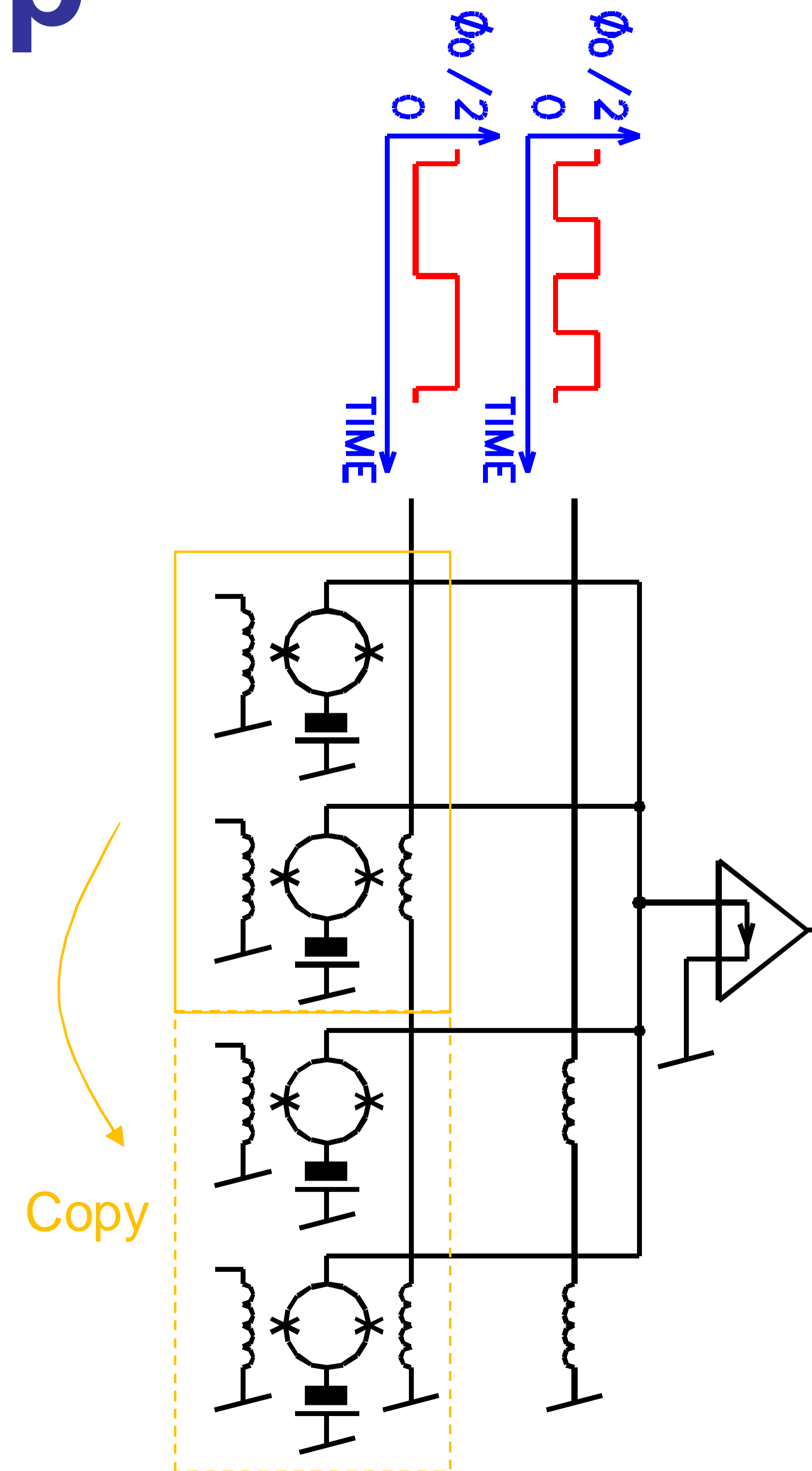


The primitive Hadamard matrix



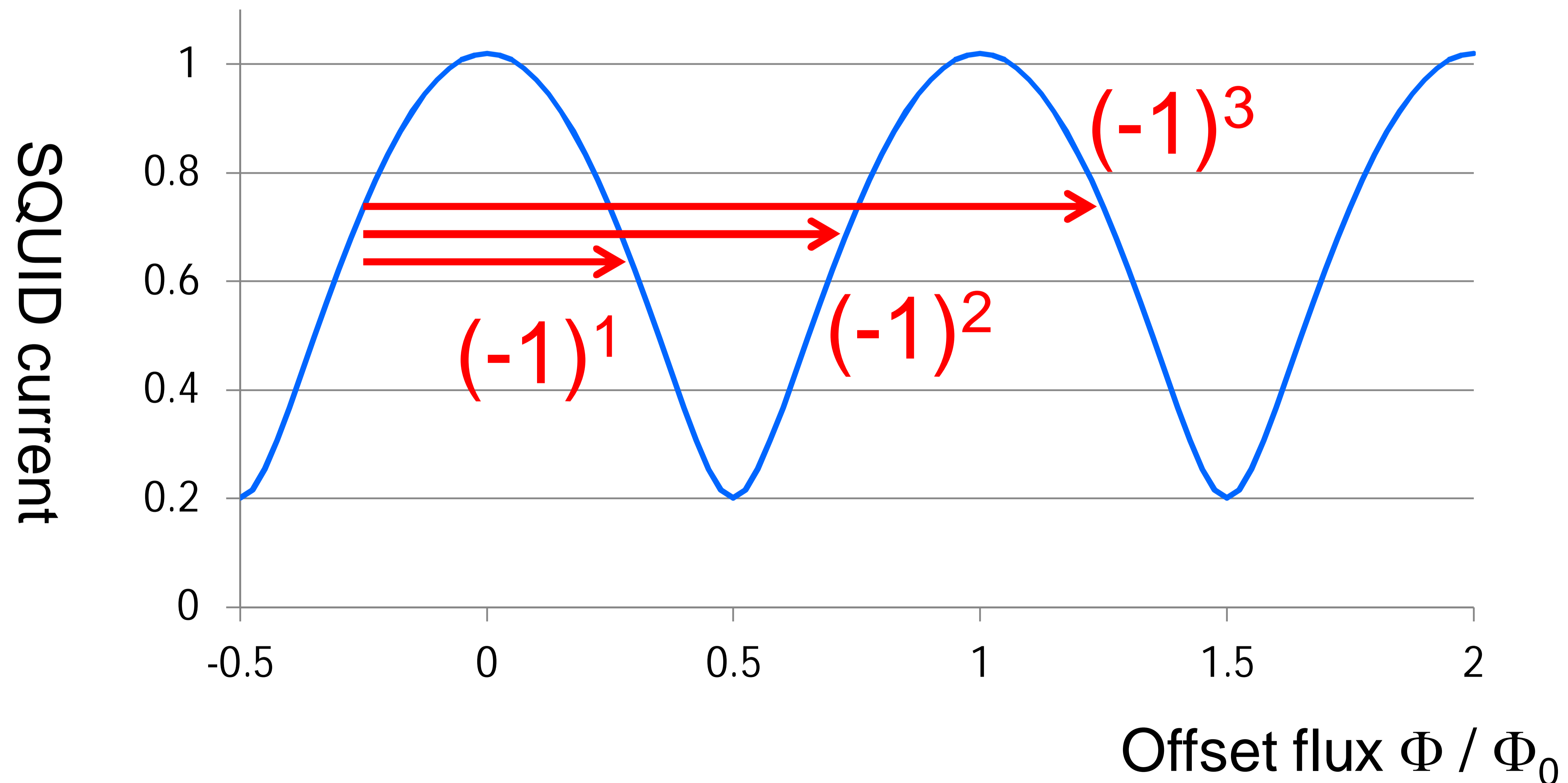
First recursive step

$$\left[\begin{array}{c} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \\ \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \end{array} \right] - \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$



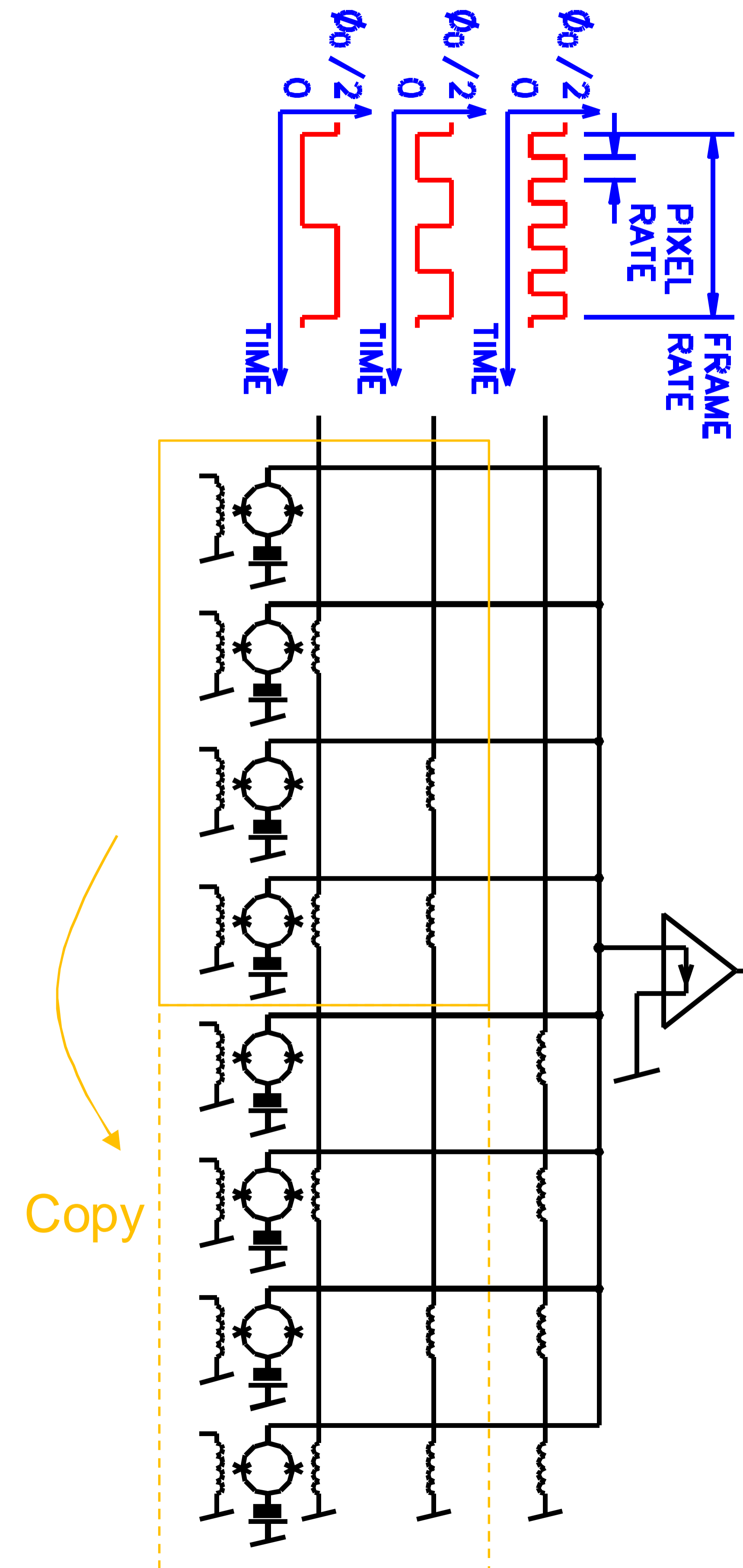
Successive multiplications by -1

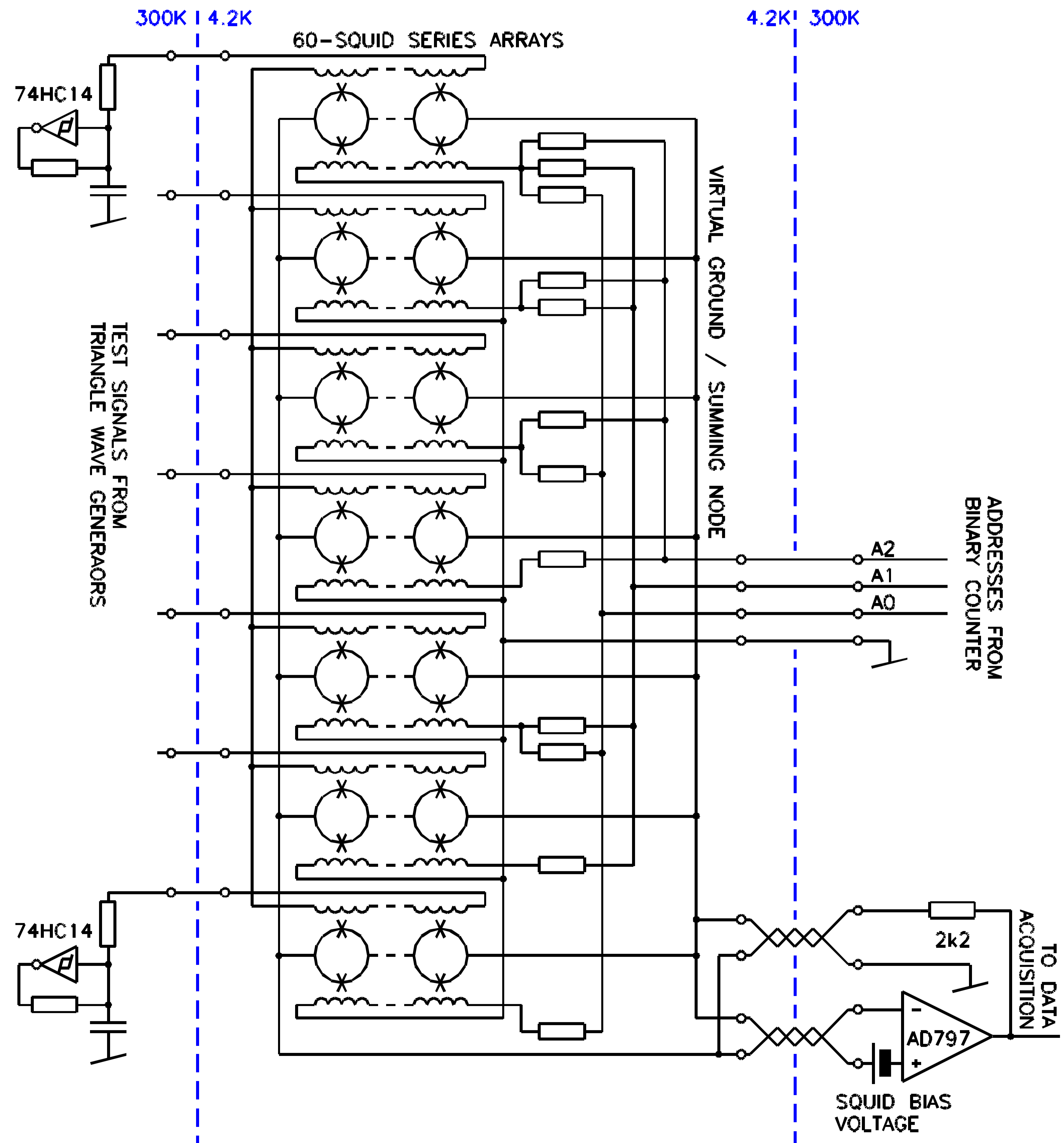
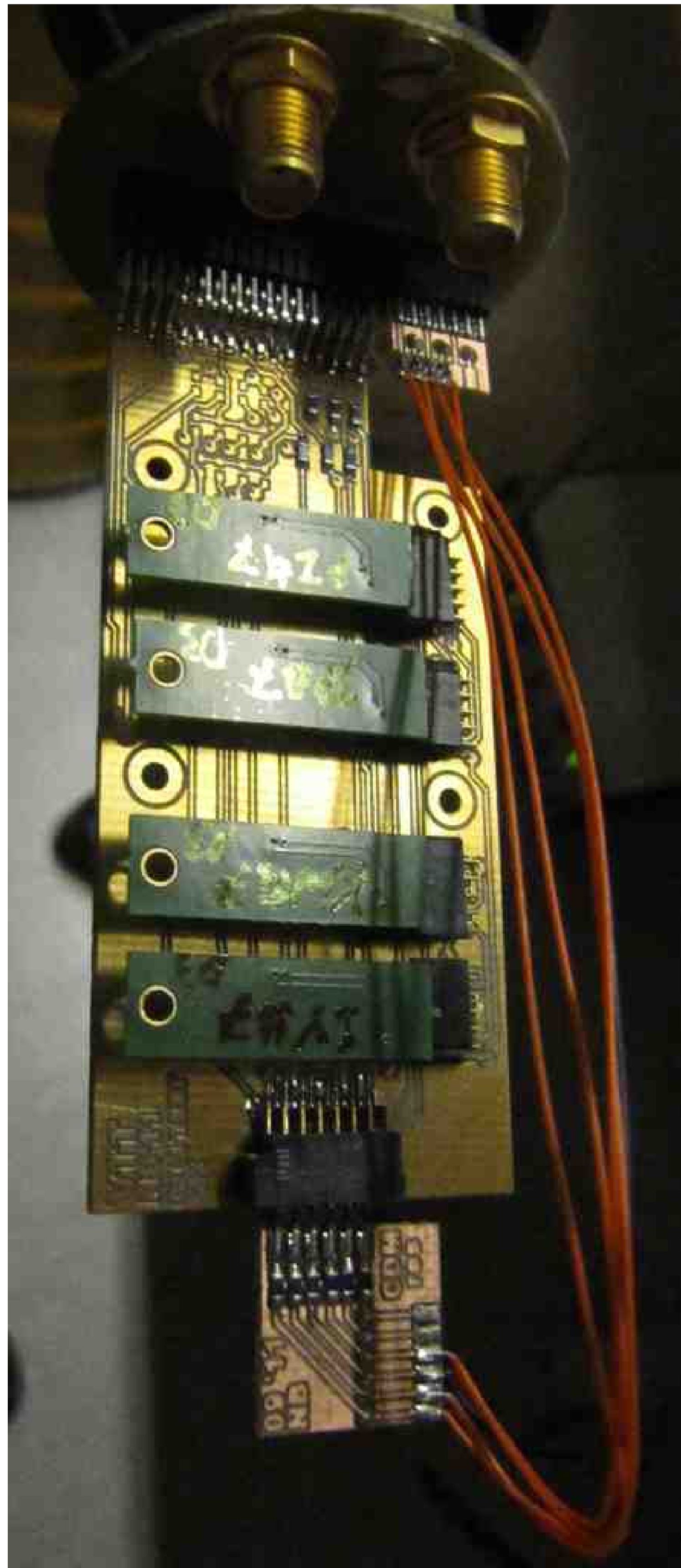
⇔ Successive $\Phi_0 / 2$ flux shifts



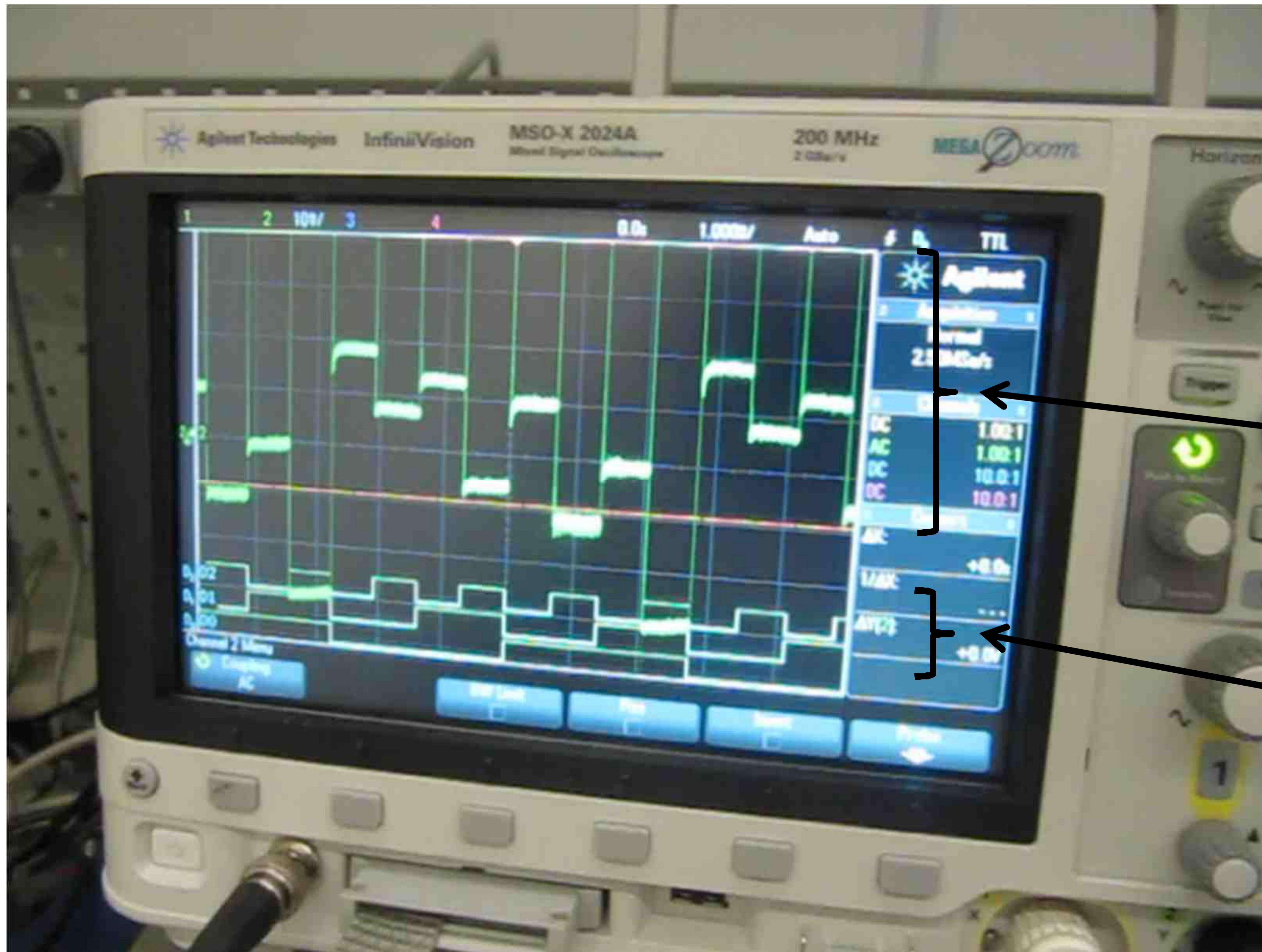
Second recursive step

$$\left[\begin{array}{cccc} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \\ \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & - \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & - \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \\ \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & - \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & - \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \\ \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & - \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & - \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} & \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \end{array} \right]$$





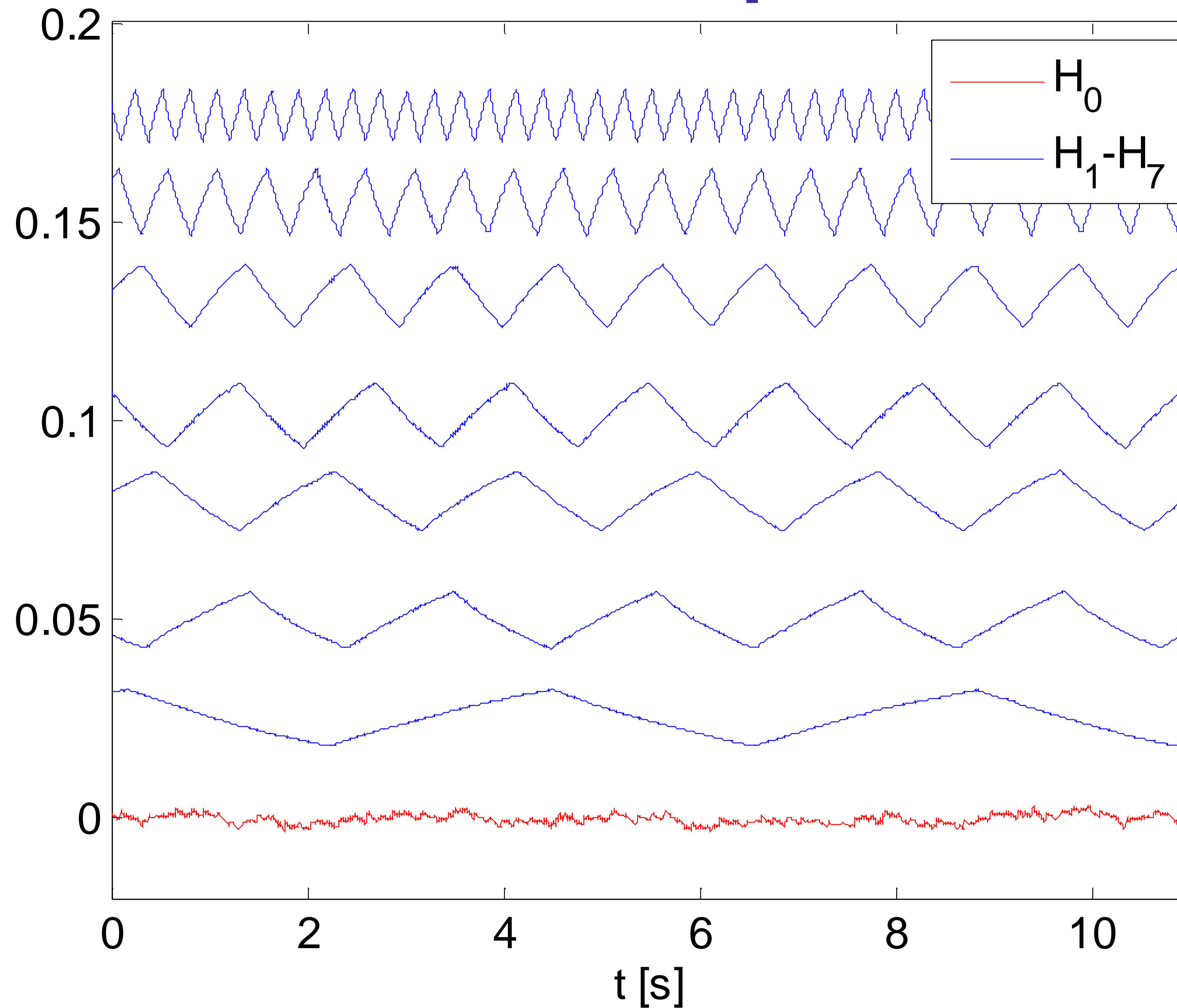
7-ch Hadamard coded output, one input driven by sawtooth



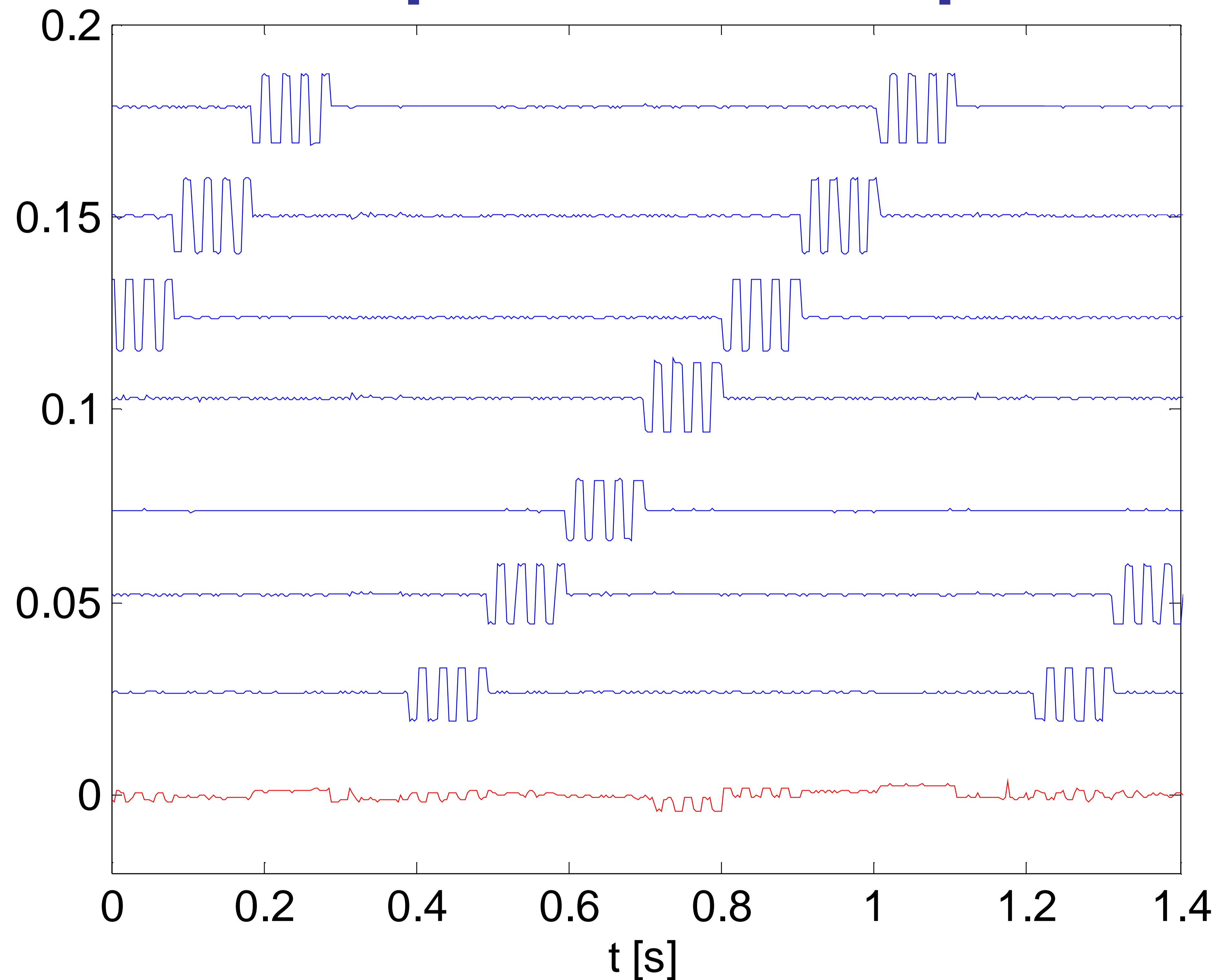
Summed output from SQUIDs

3-bit binary address at 2500 pix/s

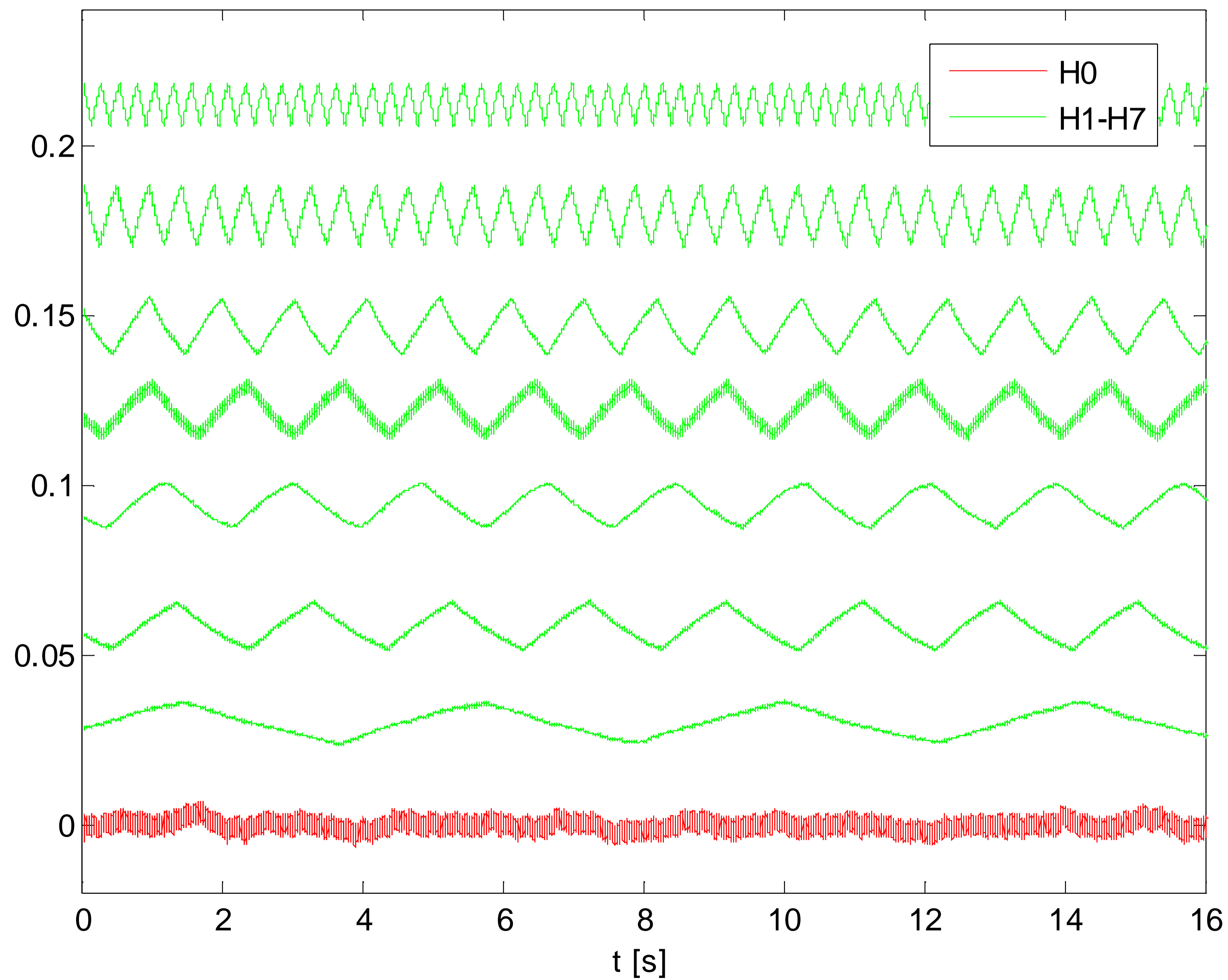
Seven test signals multiplexed and demultiplexed at 2.5 kpix/s



Seven calibration signals multiplexed and demultiplexed at 2.5 kpix/s



Seven test signals multiplexed and demultiplexed at 30 kpix/s



What have we learned, achieved?

- Log N scaling (binary addressing) is much more efficient than $N^{1/2}$ scaling, inherent in NIST-style TDM.
Example: 16 384 pixels require 128 address lines via TDM, 14 address lines via binary-addressed CDM.
- Slope-switching adds SQUID noise $\sim N^{1/2}$.
Unattractive, but no worse than the noise penalty in TDM.
- Our design of current-steering switches may be misguided.
More complicated than the NIST design, complexity offers many paths for faulty operation.
- Cryogenic setup with X-ray calorimeters is almost ready
Thermalization problem must be solved
- Cross-compatible fab process, IPHT Jena \Leftrightarrow VTT Espoo

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Thank You!